## TIF 150: Information theory for complex systems

Time: March 14, 2014, 14.00-18.00
Allowed material: Calculator (type approved accordingly to Chalmers rules).
Teacher (available during exam): Kristian Lindgren (7723131)
Examiner: Kristian Lindgren

All answers and derivations must be clear and well motivated.
Grade limits: 25 p for 3,34 p for 4,42 p for 5 . Points from homework problems and project may be included, but a minimum of 20 p is required on the written exam.
The results will be available on April 4.

## 1. Finding the deviating ball 8 p

You have 13 almost identical balls. The only difference between them is that one of them have a slightly deviating weight, it could be heavier, or lighter. You are tasked to find which of the balls that deviates, with only the means of a balance scale (that tips to the side with the heaviest load, or remains in balance if the two sides are of equal weight) and three measurements.
a) How large is the entropy of the system? How large is the entropy of which of the 13 balls that deviates?
b) Assuming ideal measurements, how many measurements would you need at least to find the deviating one?
c) Find a procedure to identify the deviating ball using a balance scale and only three measurements. You need only to describe the procedure assuming the worst case outcome for each measurement (the most probable outcome), i.e. not all possible branches of measurements.

## 2. Rubber band. 10p

A well known elasticity model for rubber bands is a one dimensional system of cells/parts that can either be contracted or extended. The contracted elements can be called C and the extended ones can be called E . Let the extended ones contribute with -J to the total energy of the system and have length $a$, the contracted ones have length $a / 2$ and contribute with 0 to the total energy. If the average length is $L$, what is the equilibrium distribution (You may give the answer as a function of temperature)? What happens if you heat a rubberband?

## 3. CA information. 8p

Consider a one-dimensional cellular automaton given by rule 238 ( 100 and 000 maps to 0 , the rest to 1 ). Let the initial state be characterized by the following finite state automaton (where it is assumed that if two arcs leave the same node, they have equal probabilities).

a) What is the initial entropy (at $\mathrm{t}=0$ )?
b) Derive the finite state automaton that characterizes the CA state after one time step $(\mathrm{t}=1)$.
c) What is the entropy at $(t=1)$ ? At $(t=$ infinity $)$ ?

## 4. Correlation complexity. 12p

Below are a hidden Markov model, when two arcs leave a node it is assumed that they have the same probability.

a) How long correlations (in information theoretical terms) are present in the system?
b) Determine the correlation complexity.

## 5. Chaos and information. 12p

Let a piecewise linear map be defined by the figure below, where $a<1$ and where the mapping is determined by:


Consider the dynamic system given by

$$
x_{t+1}=f\left(x_{t}\right)
$$

a) Start with $a$ close to 0 and let $a$ increase. Determine whether there is a stable fix point, stable periodic orbit (you don't have to find the periodicity) or chaos. At what value for $a$ is there a change to the dynamical characteristics?
b) Suppose that $a=1 / 3$. Determine the invariant measure that characterizes the chaotic behavior, and calculate the Luyapunov exponent. Find a partition that is generating, and calculate the measure entropy from the symbolic dynamics.

## Information theory for complex systems - useful equations

Basic quantities
$I(p)=\log \frac{1}{p}$
$S[P]=\sum_{i=1}^{n} p_{i} \log \frac{1}{p_{i}}$
$K\left[P^{(0)} ; P\right]=\sum_{i=1}^{n} p_{i} \log \frac{p_{i}}{p_{i}^{(0)}}$

Max entropy formalism (with $k+1$ constraints) using the Lagrangian $L$

$$
\begin{aligned}
& L\left(p_{1}, \ldots, p_{n}, \lambda_{1}, \ldots, \lambda_{r}, \mu\right)=S[P]+\sum_{k=1}^{r} \lambda_{k}\left(F_{k}-\sum_{i=1}^{n} p_{i} f_{k}(i)\right)+(\mu-1)\left(1-\sum_{i=1}^{n} p_{i}\right), \\
& p_{j}=\exp \left(-\mu-\sum_{k=1}^{r} \lambda_{k} f_{k}(j)\right), \mu(\lambda)=\ln \sum_{j=1}^{n} \exp \left(-\sum_{k} \lambda_{k} f_{k}(j)\right), \frac{\partial \mu(\lambda)}{\partial \lambda_{k}}=-F_{k}
\end{aligned}
$$

Symbol sequences

$$
\begin{aligned}
& s=\lim _{n \rightarrow \infty} \sum_{x_{1} \ldots x_{n-1}} p\left(x_{1} \ldots x_{n-1}\right) \sum_{x_{n}} p\left(x_{n} \mid x_{1} \ldots x_{n-1}\right) \log \frac{1}{p\left(x_{n} \mid x_{1} \ldots x_{n-1}\right)}= \\
& \\
& =\lim _{n \rightarrow \infty}\left(S_{n}-S_{n-1}\right)=\Delta S_{\infty}=\lim _{n \rightarrow \infty} \frac{1}{n} S_{n} \\
& k_{1}=\log v-S_{1}, \quad k_{n}=-S_{n}+2 S_{n-1}-S_{n-2}=-\Delta S_{n}+\Delta S_{n-1}=-\Delta^{2} S_{n} \quad(n=2,3, \ldots) \\
& S_{\text {tot }}=\log v=\sum_{m=1}^{\infty} k_{m}+s \\
& \eta=\sum_{m=1}^{\infty}(m-1) k_{m}=\lim _{m \rightarrow \infty} \lim _{n \rightarrow \infty} \sum_{\sigma_{m}} p\left(\sigma_{m}\right) \sum_{\tau_{n}} p\left(\tau_{n} \mid \sigma_{m}\right) \log \frac{p\left(\tau_{n} \mid \sigma_{m}\right)}{p\left(\tau_{n}\right)}=\lim _{m \rightarrow \infty}\left(S_{m}-m s\right)
\end{aligned}
$$

Geometric information theory

$$
\begin{array}{ll}
p(r ; x)=\frac{1}{\sqrt{2 \pi} r} \int_{-\infty}^{\infty} d w e^{-w^{2} / 2 r^{2}} p(x-w), & \left(-r \frac{\partial}{\partial r}+r^{2} \frac{d^{2}}{d x^{2}}\right) p(r ; x)=0 \\
p_{\text {Gaussian }}(r ; x)=\frac{1}{\sqrt{2 \pi} \sqrt{b^{2}+r^{2}}} \exp \left(-\frac{x^{2}}{2\left(b^{2}+r^{2}\right)}\right) & \\
K\left[p_{0} ; p\right]=\int d x p(x) \ln \frac{p(x)}{p_{0}(x)}=\int_{0}^{\infty} \frac{d r}{r} \int d x k(r, x), & k(r, x)=r^{2} p(r ; x)\left(\frac{d}{d x} \ln p(r ; x)\right)^{2} \\
d(r)=D_{\mathrm{E}}-r \frac{\partial}{\partial r} \int d \mathbf{x} p(r ; \mathbf{x}) \ln \frac{1}{p(r ; \mathbf{x})}
\end{array}
$$

Chemical systems and information flow

$$
E=k_{\mathrm{B}} T_{0} \frac{N}{V} K, \quad K=\int_{V} d \mathbf{x} K\left[c_{0} ; c(\mathbf{x})\right]=\int_{V} d \mathbf{x} \sum_{i=1}^{M} c_{i}(\mathbf{x}) \ln \frac{c_{i}(\mathbf{x})}{c_{i 0}}, \quad \sum_{i=1}^{M} c_{i}(\mathbf{x}, t)=1
$$

$$
\begin{aligned}
& K=V \sum_{i=1}^{M} \bar{c}_{i} \ln \frac{\bar{c}_{i}}{c_{i 0}}+\int_{V} d \mathbf{x} \sum_{i=1}^{M} c_{i}(\mathbf{x}) \ln \frac{c_{i}(\mathbf{x})}{\bar{c}_{i}}=K_{\text {chem }}+K_{\text {spatal }} \\
& K_{\text {spatial }}=\int_{0}^{\infty} \frac{\partial r}{r} \int d \mathbf{x} k(r, \mathbf{x}) \\
& k(r, \mathbf{x})=r^{2} \sum_{i} \tilde{c}_{i}(r, \mathbf{x})\left(\nabla \ln \frac{\tilde{c}_{i}(r, \mathbf{x})}{c_{i 0}}\right)^{2}=r^{2} \sum_{i} \frac{\left(\nabla \tilde{c}_{i}(r, \mathbf{x})\right)^{2}}{\tilde{c}_{i}(r, \mathbf{x})}=\left(-r \frac{\partial}{\partial r}+r^{2} \nabla^{2}\right) \sum_{i} \tilde{c}_{i}(r, \mathbf{x}) \ln \frac{\tilde{c}_{i}(r, \mathbf{x})}{c_{i 0}} \\
& \dot{c}_{i}(\mathbf{x}, t)=\frac{d}{d t} c_{i}(\mathbf{x}, t)=D_{i} \nabla^{2} c_{i}(\mathbf{x}, t)+F_{i}(\mathbf{c}(\mathbf{x}, t))+b_{i}\left(c_{i, \text { res }}-c_{i}(\mathbf{x}, t)\right) \\
& \sigma(\mathbf{x}, t)=\sum_{i}\left(D_{i} \frac{\left(\nabla c_{i}(\mathbf{x}, t)\right)^{2}}{c_{i}(\mathbf{x}, t)}-F_{i}(\mathbf{c}(\mathbf{x}, t)) \ln \frac{c_{i}(\mathbf{x}, t)}{c_{i 0}}\right) \\
& j_{r}(r, \mathbf{x}, t)=\sum_{i}\left(D_{i} \frac{\left(\nabla \tilde{c}_{i}(r, \mathbf{x}, t)\right)^{2}}{\tilde{c}_{i}(r, \mathbf{x}, t)}-\tilde{F}_{i}(\mathbf{c}(\mathbf{x}, t)) \ln \frac{\tilde{c}_{i}(r, \mathbf{x}, t)}{c_{i 0}}\right), \tilde{F}_{i}(\mathbf{c}(\mathbf{x}, t))=\exp \left(\frac{r^{2}}{2} \nabla^{2}\right) F_{i}(\mathbf{c}(\mathbf{x}, t)) \\
& \mathbf{j}(r, \mathbf{x}, t)=-r^{2} \nabla \sum_{i} \tilde{F}_{i}(\mathbf{c}(\mathbf{x}, t)) \ln \frac{\tilde{c}_{i}(r, \mathbf{x}, t)}{c_{i 0}}, J(r, x, t)=-\sum_{i} b_{i}\left(\tilde{c}_{i}+c_{i, \text { res }}\right)\left[r \nabla \ln \tilde{c}_{i}\right]^{2} \\
& \dot{k}(r, \mathbf{x}, t)=r \frac{\partial}{\partial r} j_{r}(r, \mathbf{x}, t)-\nabla \cdot \mathbf{j}(r, \mathbf{x}, t)+J(r, x, t)
\end{aligned}
$$

## Chaos and information

$\int d x \mu(x) \varphi(x)=\lim _{T \rightarrow \infty} \frac{1}{T} \sum_{k=0}^{T-1} \varphi\left(f^{k}(x(0))\right)$,
$\lambda=\lim _{t \rightarrow \infty} \frac{1}{t} \sum_{k=0}^{t-1} \ln \left|f^{\prime}(x(k))\right|=\int d x \mu(x) \ln \left|f^{\prime}(x)\right|$
$h(\mu, \mathbf{A})=\lim _{n \rightarrow \infty} \frac{1}{n} H\left(B^{(n)}\right)=\lim _{n \rightarrow \infty}\left(H\left(B^{(n+1)}\right)-H\left(B^{(n)}\right)\right), \quad s_{\mu}=\lim _{\operatorname{diam}(\mathbf{A}) \rightarrow 0} h(\mu, \mathbf{A}), s_{\mu}=\lambda$

2014-(1) 13 balls, one deviates: heavy or light
entropy of system $S=\log (2.13)=\log 26$ entropy of problem (finding the deviating one): $S=\log 13$
ideal measurments awe arranged so that you get $\log 3$ information, i.e., equally probable outcomes!
Then, theoretically, 3 measurments may work since $3 \cdot \log 3>\log 13$.
4 vs 4,5 aside $\rightarrow$ "worst" or most probable outcome is "balanced"

5 remains $S_{1}=\log 5<2 \log 3$, $O K$.
take three of these and a normal one $\theta$
$\frac{0000}{\lambda} 00$
balanced result most probable: $S_{2}=\log 2<\log 3$ or!
on of the two against $(\mathcal{O}$ determines the deviation one. $S_{3}=0$

2014-(2) Rubber band


$$
h(c)=-J, h\left(E_{\zeta}\right)=0
$$

contracted extender

$$
\text { longer } a / 2 \text { length a }
$$

You can pick cither an energy constraint or
a length constraint (Since the length constant is an energy constraint). with encrergy $u=-J p(E)$ and with

No interactions between neighbour states you get :
$P(E)=\frac{e^{\beta J}}{1+e^{\beta J}}$ and $p(C)=\frac{1}{1+e^{B J}}$ where $\beta=\frac{1}{k_{3} T}$ is Lagrange variable for the energy constraint
average length $L=p(C) \frac{a}{2}+p(D) a=\frac{\frac{1}{2}+e^{\beta J}}{1+e^{\beta J}}=1-\frac{1}{2} \frac{1}{1+e^{\beta \nu}}$ So if Tincreaser, $\beta$ decreases, and $L$ decreases!

2014-(3) CA-rule 238: O00 $\rightarrow 0,100 \rightarrow 0$, oth $\rightarrow 1$


As betire, we find $s=\frac{2}{7} \log 2$.
cA rute

$$
t=2
$$



CA nule

$$
t \geq 3
$$



$$
\Rightarrow s=0
$$

2014-(4) Corelation complexity


$$
k_{m}=\sum p\left(x_{1} \cdots x_{m-1}\right) \sum_{x_{m}} p\left(x_{m} \mid x_{1} \cdot x_{m-1}\right) \log \frac{p\left(x_{m} \mid x_{1} \cdots x_{m-1}\right)}{p\left(x_{m} \mid x_{2} \cdots x_{m-1}\right)}
$$

$$
k_{m}=0 \text { only if } p\left(x_{m} \mid x_{1} \cdot x_{m-1}\right)=
$$

$$
=p\left(\alpha_{m} \mid \alpha_{2} \ldots \alpha_{m-1}\right)
$$

for all sequences
But this equality carnot hold when $x_{2} \ldots x_{m-1}$ are only $O^{\prime}$ s, since $x_{1}=1$ will determine which node we are $\mathrm{in} . \rightarrow k_{m}>0$ all $m$.

Repeating the derivation in the lecture notes we find:

$$
\eta=\sum_{z} p(z) \log \frac{1}{p(z)}-\lim _{m \rightarrow \infty} \sum_{T_{n}} p\left(\tau_{m}\right) \sum_{z} p\left(z \mid T_{n}\right) \log \frac{1}{p\left(z \mid T_{m}\right)}
$$

where $z$ is a horde and $T_{h}$ is the following sequence. (In the derivation we have used the fact that a preceding sequence $\sigma_{m}$ almost always deterimes the node $z$ in the limit $m \rightarrow \infty$.)

The second expression quantifies the uncertainty of $n$ role $z$ when we observe $\tau$ (in average). If $\tau$ starts $w$. an even number of $O^{\prime}$ 's we cannot know whether me started in the left or sin the bottom node. The probability for such a sequence from the left node is $p(\mu \mathrm{ft}) \cdot \frac{1}{2}=\frac{1}{5}$ and form the bottom node $P($ bottom $)=\frac{1}{5}$. This gives that the second expression is $\frac{2}{5} \log 2$ (since the uncertainty of $z$-node is ane bit in this case. And

$$
S=\frac{1}{5} \log 5+2 \cdot \frac{2}{5} \log \frac{5}{2}-\frac{2}{5} \log 2=\log 5-\frac{6}{5} \log 2
$$

2014-(5) Chaos Solution sketch!

$A B C$
small $a: A \rightarrow B \rightarrow C \rightarrow A \ldots \quad \mu(A)=\mu(B)=\mu(C)=\frac{1}{3}$

$$
\begin{aligned}
& \lambda=\frac{1}{3}(\ln 2+\ln 2+\ln (3 a)) \\
& \lambda<0 \text { if } 2 \cdot 2 \cdot 3 a<1 \Rightarrow a<\frac{1}{12}
\end{aligned}
$$

$\Rightarrow$ stable periodic orbit if $a<\frac{1}{12}$.
We also check that we stay within $A \rightarrow B \rightarrow C \rightarrow A \ldots$

$$
x_{0}=1 \supset \underbrace{\alpha_{1}=a}_{\in A} \gg \underbrace{x_{2}=\frac{2}{3}-2 a}_{\epsilon B} \gtrdot x_{3}=-\frac{1}{3}+2\left(\frac{2}{3}-2 a\right)=\underbrace{1-4 a}_{\epsilon C}
$$

We note that as $a>1 / 12, x_{3}$ does not always get bade in $C$, ie, we spend more time in $A$ and $B$ which amplifies the value of $\lambda$, clearly showing that $\lambda>0$ for $a>\frac{1}{12} \Rightarrow$ chaos.
For $a=\frac{1}{3},\{A, B, C\}$ is a generating partition.
Invariant measure $\mu(A)=\mu(B)=\frac{2}{5}, \mu(C)=\frac{1}{5}$

$$
\begin{align*}
& \lambda=\frac{4}{5} \ln 2+\frac{1}{5} \ln 1=\frac{4}{5} \ln 2  \tag{A}\\
& S_{\mu}=2 \cdot \frac{2}{5} \ln 2=\frac{4}{5} \ln 2
\end{align*}
$$

