INSTRUCTOR'S MANUAL

To Accompany

ENGINEERING MECHANICS - DYNAMICS

Volume 2

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USE OF THE INSTRUCTOR'S MANUAL

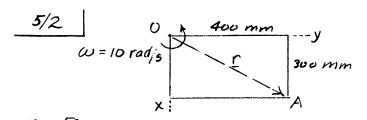
The problem solution portion of this manual has been prepared for the instructor who wishes to occasionally refer to the authors' method of solution or who wishes to check the answer of his (her) solution with the result obtained by the authors. In the interest of space and the associated cost of educational materials, the solutions are very concise. Because the problem solution material is not intended for posting of solutions or classroom presentation, the authors request that it not be used for these purposes.

In the transparency master section there are approximately 65 solved problems selected to illustrate typical applications. These problems are different from and in addition to those in the textbook. Instructors who have adopted the textbook are granted permission to reproduce these masters for classroom use.

$$\frac{5/1}{\omega_2^2 = \omega_1^2 + 2\alpha\theta} \propto \frac{800 - 200}{4/60} = 9000 \text{ rev/min}^2$$

$$\omega_2^2 = \omega_1^2 + 2\alpha\theta, \quad 800^2 = 200^2 + 2(9000)\theta \quad (\text{rev/min})^2$$

$$\theta = \frac{800^2 - 200^2}{2(9000)} = 33.3 \text{ rev} = N$$



 $r = 500 \, \text{mm}$ or $0.5 \, \text{m}$ (a) $5 \, \text{calar}$: $V = r\omega = 0.5 \, (10) = 5 \, \text{m/s}$

 $a=q_n=r\omega^2=0.5(10^2)=50 \text{ m/s}^2$

(6)
$$\Gamma = 0.3i + 0.4j \text{ m}, \quad \omega = 10k \text{ rad/s}$$

$$U = \omega \times r = 10k \times (0.3i + 0.4j) = 3j + 4(-i)$$

$$V = \sqrt{3^2 + (-4)^2} = \frac{5m/s}{4}$$

$$a = \omega \times r + \omega \times \dot{r} = 0 + \omega \times U$$

$$= 0 + 10k \times (3j - 4i) = -30i - 40j \text{ m/s}^2$$

$$10 = \sqrt{30^2 + 40^2} = \frac{50m/s^2}{40^2}$$

5/3 Let k be a unit vector out of paper.

(a) $V_A = \omega \times r_{A/0} = 3k \times (-0.4e_n) = 1.2e_t m/s$ $a_A = \alpha \times r_{A/0} - \omega^2 r_{A/0} = -14k \times (-0.4e_n) -3^2 (-0.4e_n)$ $= -5.6e_t + 3.6e_n m/s^2$

(b)
$$v_B = \omega \times r_{B/o} = 3k \times (-0.4e_n + 0.1e_t)$$

= $1.2e_t + 0.3e_n m/s$

$$\frac{a_{B}}{=} = \frac{x_{B/0}}{-\omega^{2}} \frac{r_{B/0}}{r_{B/0}}$$

$$= -14 k_{X}(-0.4 e_{n} + 0.1 e_{t}) - 3^{2}(-0.4 e_{n} + 0.1 e_{t})$$

$$= -6.5 e_{t} + 2.2 e_{n} \text{ m/s}^{2}$$

$$\frac{5/4}{\omega_{ov}} = \frac{\omega_{ort}}{\omega_{ort}} = \frac{\omega_{o}}{\omega_{o}} = \frac{\frac{14.20}{56-8}}{\frac{12.25}{560}} = \frac{3.55}{\frac{rad}{560}}$$

$$\omega_{ov} = \frac{\Delta\Theta}{\Delta t} = \frac{\pi/4}{0.638} = \frac{1.231 \text{ rod/sec}}{\frac{12.25}{560}}$$

5/5 For
$$\theta = 90^{\circ}$$
, $a = -a_{t}i - a_{n}j$ so $a_{t} = r\alpha = 1.8 \text{ m/s}^{2}$, $\alpha = \frac{1.8}{0.3} = \frac{6 \text{ rad/s}^{2}}{0.3}$

$$4 a_{n} = r\omega^{2} = 4.8 \text{ m/s}^{2}, \ \omega = \sqrt{4.8/0.3} = \frac{4 \text{ rad/s}}{4 \text{ rad/s}}$$

$$a_t = r\alpha$$
: $\alpha = 1.803/0.3 = 6.01 \text{ rad/s}^2$
 $a_n = r\omega^2$: $\omega^2 = 2.92/0.3 = 9.72 (rad/s)^2$, $\omega = 3.12 \text{ rad/s}$

5/7
$$\theta = 2t^3 - 3t^2 + 4 \text{ rad.}$$

 $\dot{\theta} = 6t^2 - 6t \text{ rad/s}$
 $\ddot{\theta} = 12t - 6 \text{ rad/s}^2$
When $\ddot{\theta} = 42 \text{ rad/s}^2$, $42 = 12t - 6$, $t = 4s$
when $\ddot{\theta} = 66 \text{ rad/s}^2$, $66 = 12t - 6$, $t = 6s$
 $\theta = 2(4^3) - 3(4^2) + 4 = 84 \text{ rad}$
 $t = 4s$
 $\theta = 2(6^3) - 3(6^2) + 4 = 328 \text{ rad}$
 $\theta = 328 - 84 = 244 \text{ rad}$

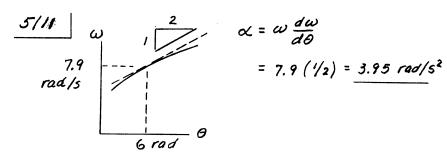
For point P,
$$a = -3i - 4j \text{ m/s}^2$$
 $a_n = r\omega^2$, $4 = 0.5 \omega^2$, $\omega = \sqrt{8} \frac{\text{rod}}{s}$
 $\omega = -\sqrt{8} \frac{\text{k}}{\text{rad/s}}$
 $a = r\alpha$, $a = 0.5\alpha$, $\alpha = 6 \frac{\text{rad/s}^2}{s}$
 $\alpha = 6 \frac{\text{k}}{\text{rad/s}^2}$

 $\begin{array}{c|c}
5/9 & a_{g} = q = r\alpha \\
\omega = \omega + \alpha t : 300(2\pi)/_{60} = 0 + \alpha(2), \alpha = 5\pi rad/_{5}^{2} \\
7hus & 5.5 = r(5\pi), r = 0.350m \\
b = \sqrt{0.350^{2} - 0.3^{2}} = 0.1806 \text{ m or } b = 180.6 \text{ mm}
\end{array}$

Note that \underline{r} could have been taken as $0.5\underline{i} + 0.2\underline{j}$ m. The magnitudes of the above results are $v_p = 1.077$ m/s and $v_p = 2.69$ m/s².

These magnitudes check with

$$\begin{aligned}
\nu_{p} &= \Gamma_{xy} \omega = \sqrt{0.5^{2} + 0.2^{2}} \left(2\right) = 1.077 \text{ m/s}^{2} \\
\text{and } \alpha_{p} &= \sqrt{\alpha_{t}^{2} + \alpha_{n}^{2}} = \sqrt{(\Gamma_{xy} \alpha)^{2} + (\Gamma_{xy} \omega^{2})^{2}} \\
&= \sqrt{0.5^{2} + 0.2^{2}} \sqrt{3^{2} + 2^{4}} = 2.69 \text{ m/s}^{2}
\end{aligned}$$



$$c = \omega \frac{d\omega}{d\theta}$$

= 7.9 (1/2) = 3.95 rad/5²

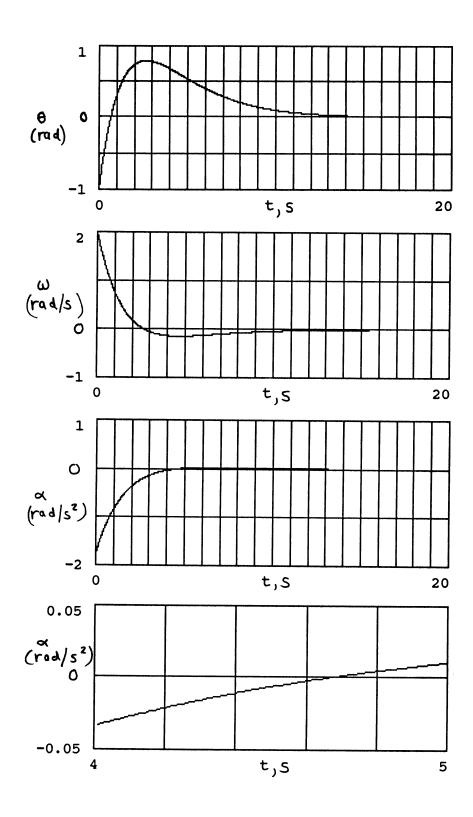
$$\frac{5/12}{\omega = \frac{d\theta}{dt}} = (-1+1.5t)e^{-0.5t}$$

$$\omega = \frac{d\theta}{dt} = -0.5(-1+1.5t)e^{-0.5t} + 1.5e^{-0.5t}$$

$$= (2-0.75t)e^{-0.5t}$$

$$\alpha = \frac{d\omega}{dt} = -0.5(2-0.75t)e^{-0.5t} - 0.75e^{-0.5t}$$
$$= (-1.75 + 0.375t)e^{-0.5t}$$

$$\alpha = 0$$
 when $-1.75 + 0.375t = 0, $t = 4.67s$$

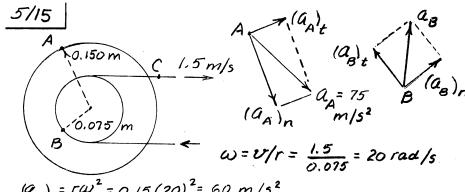


5//3
$$\omega_{0A} = \omega_{Bc} = -6k \text{ rad/s}$$
 $\Gamma_{A} = 0.3i + 0.28j \text{ m}$
 $U_{A} = \omega \times \Gamma_{A} = -6k \times (0.3i + 0.28j) = -1.8j + 1.68i \text{ m/s}$
 $U_{A} = \omega \times \Gamma_{A} + \omega \times V_{A} = 0 + (-6k) \times (1.68i - 1.8j)$
 $U_{A} = 0.8i - 10.08j \text{ m/s}^{2}$

$$5/14$$
 At B, $\sigma = \frac{50}{30}44 = 73.3$ ft/sec, $r = 180 - \frac{18}{12} = 178.5$ ft

$$\omega = \sigma/r = 73.3/178.5 = 0.411 \ rad/sec$$

Between
$$A \notin B$$
 $\omega_{av} = \frac{\Delta \theta}{\Delta t} = \frac{30}{180} \pi / 1.52 = \frac{0.344 \text{ rad/sec}}{180}$



$$(Q_{A})_{n} = r\omega^{2} = 0.15(20)^{2} = 60 \text{ m/s}^{2}$$

$$(O_{A})_{t} = \sqrt{(75)^{2} - (60)^{2}} = 45 \text{ m/s}^{2}$$

$$\alpha = a_{t}/r = 45/0.15 = 300 \text{ rad/s}^{2}$$

$$(a_{B})_{n} = 0.075(20)^{2} = 30 \text{ m/s}^{2}$$

$$(a_{B})_{t} = r\alpha = 0.075(300) = 22.5 \text{ m/s}^{2}$$

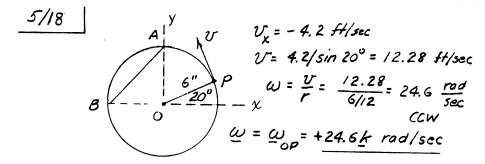
$$a_{B} = \sqrt{(30)^{2} + (22.5)^{2}} = 37.5 \text{ m/s}^{2}$$

$$a_{C} = a_{B} = 22.5 \text{ m/s}^{2}$$

5/16
$$a = q_n = \frac{v^2}{r}, (\frac{v^2}{r})_A = \frac{4}{3}(\frac{v^2}{4})_B$$

$$r = \frac{4}{4/3} = \frac{3 \text{ in.}}{4}$$

 $5/17 \quad V_{A} = \omega \times V_{A}; \quad 8j = \omega \times 4i, \quad \omega = 2 \text{ rad/sec}$ $\omega = 2k \text{ rad/sec}$ $(a_{B})_{i} = \alpha \times V_{B}; \quad 6i = \alpha k \times 4j, \quad \alpha = -3/2 \text{ rad/sec}^{2}$ $C = \frac{4}{\sqrt{2}}(i-j) \text{ in.}$ $a_{C} = \alpha \times C + \omega \times (\omega \times C)$ $= -\frac{3}{2}k \times \frac{4}{\sqrt{2}}(i-j) + 2k \times (2k \times \frac{4}{\sqrt{2}}[i-j])$ $= \frac{6}{\sqrt{2}}(-i-j) + \frac{16}{\sqrt{2}}(-i+j) = \sqrt{2}(-11i+5j) \text{ in./sec}^{2}$



Element BC remains parallel to 2-axis so has no angular velocity

$$5/19 \quad \alpha = \frac{d\omega}{dt} = 2 - kt = 2 - 0.2t$$

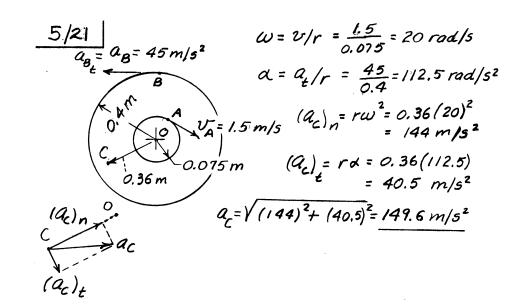
$$\int d\omega = \int (2 - 0.2t) dt, \quad \omega = \omega_0 + 2t - 0.1t^2$$

$$\omega_0 = 200 \times 2\pi/60 = 20.9 \text{ rad/s}$$

$$For t = 5s, \quad \omega = 20.9 + 2(5) - 0.1(5^2) = 28.4 \text{ rad/s}$$

$$N = 28.4 \times 60/2\pi = 272 \text{ rev/min}$$

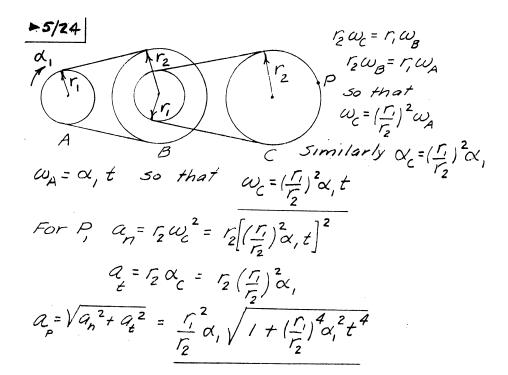
 $\omega = \omega_0 + \alpha t$: 5.60 = 0 + 10 Pt, t = 0.1784 sec



5/22 $\propto = 1.8 - k\theta \text{ rev/s}^2$, θ in revolutions 0.6 = 1.8 - k(20), $k = 0.06 \text{ '/s}^2$ $50 \propto = 1.8 - 0.06\theta \text{ rev/s}^2$; $\omega = \frac{300}{60} = 5 \text{ rev/s}$ $\omega d\omega = \alpha d\theta$: $\int_{\omega} \omega d\omega = \int_{\omega} (1.8 - 0.06\theta) d\theta$ $\omega^2 = 5^2 + 2 \left[1.8\theta - 0.03\theta^2 \right]^{20} = 25 + 48 = 73 (\text{rev/s})^2$ $\omega = \sqrt{73} = 8.54 \text{ rev/s} \text{ or } N = 8.54 (60) = 513 \text{ rev/min}$

$$\frac{5/23}{\sqrt{23}} \quad \text{For gear A, } \Delta \omega = \int_{2}^{6} \alpha_{A} dt, \quad N_{A} = 2N_{B}$$

$$(N_{A} - 600) \frac{2\pi}{60} = \frac{4+8}{2} (6-2), \quad N_{A} = 600 + 229 = 829 \text{ rev/min}$$
so at $t = 6s$, $N_{B} = \frac{829}{2} = \frac{4/5 \text{ rev/min}}{2}$



5/25
$$x = 2b \cos \theta$$
, $\dot{x} = -2b\dot{\theta} \sin \theta$, $v = \dot{x}$

$$\omega = \omega_{AB} = \dot{\theta} \quad so \quad \omega = \frac{-v}{2b \sin \theta} \quad cw$$

$$\omega = \omega_{AB} = \dot{\theta} \quad so \quad \omega = \frac{-v}{2b \sin \theta} \quad cw$$

$$\omega = \frac{v}{2b \sin \theta} \quad cw$$

$$\omega = \frac{v}{2b \sin \theta} \quad cw$$

$$v = \sqrt{2ax}$$

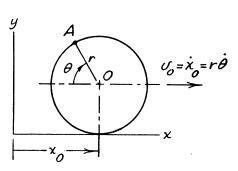
$$v = \sqrt{2ax}$$

$$2b \sqrt{1-\cos^2 \theta} = \frac{\sqrt{2ax}}{\sqrt{4b^2-x^2}}$$

$$5/26$$
 | Coordinates of A are $x = x_0 - r \cos \theta$ $y = r + r \sin \theta$

$$\dot{x} = \dot{x}_0 + r\dot{\theta}\sin\theta = v_0(1+\sin\theta)$$

$$\dot{y} = r\dot{\theta}\cos\theta = v_0\cos\theta$$



$$\begin{aligned}
\mathbf{v} &= \sqrt{\dot{x}^2 + \dot{y}^2} = \mathbf{v}_o \sqrt{(1 + \sin \theta)^2 + \cos^2 \theta} = \underline{\mathbf{v}}_o \sqrt{2(1 + \sin \theta)} \quad \mathbf{v}_o \\
\dot{\mathbf{x}} &= \mathbf{v}_o \dot{\theta} \cos \theta = \mathbf{v}_o \left(\frac{\mathbf{v}_o}{r}\right) \cos \theta = \frac{\mathbf{v}_o^2}{r} \cos \theta \\
\dot{\mathbf{y}} &= -\mathbf{v}_o \dot{\theta} \sin \theta = -\mathbf{v}_o \left(\frac{\mathbf{v}_o}{r}\right) \sin \theta = -\frac{\mathbf{v}_o^2}{r} \sin \theta
\end{aligned}$$

$$a = \sqrt{\ddot{x}^2 + \ddot{y}^2} = \frac{\sigma_0^2}{r} \sqrt{\cos^2\theta + \sin^2\theta} = \frac{\sigma_0^2}{r} \text{ toward } 0$$

5/27
$$\chi = b \tan \theta$$
, $V_{g} = \dot{\chi} = b\theta \sec^{2}\theta$

$$V_{g} = b\omega \sec^{2}\theta$$

5/28
$$v_0 = \bar{oc} \omega = \frac{\bar{cc}}{\bar{Ac}} v_A = \frac{0.9}{0.6} 0.8 = 1.2 \text{ m/s}$$

$$\omega = \frac{v_A}{\bar{Ac}} = \frac{v_0}{\bar{oc}} = \frac{1.2}{0.9} = 1.333 \text{ rad/s} . CW$$

5/29
$$V_A = r_i \omega_i = 12(2) = 24 \text{ in./sec}$$

$$V_O = \frac{\overline{OC}}{\overline{AC}} V_A = \frac{24}{32} 24 = 18 \text{ in./sec}$$

$$V_0 = \frac{OC}{AC}V_A = \frac{24}{32}24 = 18 \text{ in./sec}$$

$$S = V_0t, \quad t = \frac{100(12)}{18} = \frac{66.7 \text{ sec}}{66.7 \text{ sec}}$$

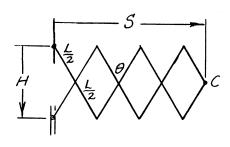
$$V_{A} = 3 \text{ ft/sec}, V_{B} = 4 \text{ ft/sec}$$

$$V_{B} = \frac{V_{B} - V_{A}}{\overline{AB}} = \frac{4 - 3}{10/12} = 1.2 \frac{rad}{sec}$$

$$V_{O} = V_{A} + \frac{\overline{A0}}{\overline{AB}} (V_{B} - V_{A})$$

$$B = 3 + \frac{4}{10} (4 - 3) = 3.4 \text{ ft/sec}$$

5/31



$$H = L \cos \frac{\theta}{2}, S = \frac{7}{2} L \sin \frac{\theta}{2}$$

$$\dot{H} = -\frac{L}{2}\dot{\theta}\sin\frac{\theta}{2} = -u, \quad \dot{S} = \omega = \frac{7}{4}L\dot{\theta}\cos\frac{\theta}{2}$$

so
$$\sigma = \frac{7}{4} L \cos \frac{\theta}{2} \left(\frac{2u}{L} / \sin \frac{\theta}{2} \right), \quad \sigma = \frac{7}{2} u \cot \frac{\theta}{2}$$

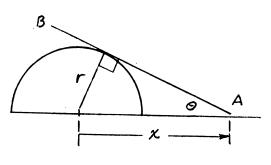
$$r = x \sin \theta$$

$$0 = \dot{x} \sin \theta + x \dot{\theta} \cos \theta$$

$$\dot{x} = \mathcal{U}, \quad \omega = \dot{\theta} \cos \theta$$

$$\omega = -\frac{\mathcal{U}}{x} \tan \theta$$

$$= -\frac{\mathcal{U}}{x} \frac{r}{\sqrt{x^2 - r^2}}$$



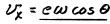
$$\begin{array}{c|c}
5/33 & V_A = r\omega_0 = -\dot{x}, & h = \chi \tan \theta \\
\omega = \dot{\alpha} = -\dot{\chi} \sin \theta \cos \theta \\
\omega = \dot{\theta} = -\dot{\chi} \sin \theta \cos \theta \\
= -\dot{\chi} \frac{h\chi}{\chi^2 + h^2} \\
\omega = \frac{rh \omega_0}{\chi^2 + h^2}
\end{array}$$

 $S = 26 \sin \theta , \quad \dot{S} = 26 \dot{\theta} \cos \theta$ $X = 26 \cos \theta , \quad \dot{X} = -26 \dot{\theta} \sin \theta = -V_{c}$ $V_{c} = \dot{S} \frac{\sin \theta}{\cos \theta} = 50 \tan 50^{\circ} = 59.6 \text{ mm/s}$

x=r+esin 0

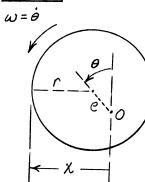
 $v_{x} = \dot{x} = 0 + e\dot{\theta}\cos\theta$





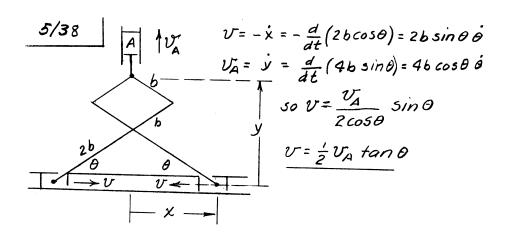
$$V_{x} = \frac{e\omega \cos \theta}{a_{x}}$$

$$a_{x} = \dot{v}_{x} = -e\omega \dot{\theta} \sin \theta = -e\omega^{2} \sin \theta$$



5/37
$$y = 0.5 \tan \theta$$

 $\dot{y} = 0.5 \sec^2 \theta \dot{\theta}$
 $\ddot{y} = 0 = \sec \theta (\tan \theta \sec \theta) \dot{\theta}^2$
 $+ 0.5 \sec^2 \theta \ddot{\theta}$
 $\dot{\theta} = -2 \tan \theta \dot{\theta}^2$
For $y = 0.6 \text{ m}$, $\tan \theta = \frac{0.6}{0.5} = 1.2$, $\theta = 50.2^\circ$
 $\sec \theta = 1.562$
So for $\dot{y} = 0.2 \text{ m/s}$, $\dot{\theta} = \frac{2(0.2)}{(1.562)^2} = 0.1639 \text{ rad/s}$
 $\ddot{\theta} = -2(1.2)(0.1639)^2 = -0.0645$

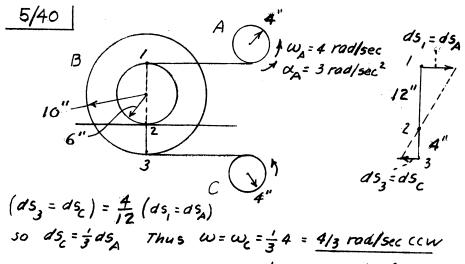


$$5^{2} = b^{2} + L^{2} - 2bL \cos \theta$$

$$25 \dot{5} = 0 + 0 + 2bL\dot{\theta} \sin \theta$$

$$\dot{\theta} = \frac{55}{bL \sin \theta}$$

So
$$V = 2b \frac{s\dot{s}}{bL \sin\theta} \cos\theta = 2 \frac{\sqrt{b^2 + L^2 - 2bL \cos\theta}}{L \tan\theta} \dot{s}$$



so
$$dS_c = \frac{1}{3}dS_A$$
 Thus $\omega = \omega_c = \frac{1}{3}A = \frac{4/3 \text{ rad/sec CCW}}{2}$
 $\alpha = \alpha_c = \frac{1}{3}B = \frac{1 \text{ rad/sec}^2 \text{ CCW}}{2}$

Let D be point on CB $d\beta \qquad dS_{A} \qquad \theta \qquad D \qquad Coincident \ with \ A$ $0.12 \qquad \beta \qquad 0.32 \qquad A \qquad 0.32 \qquad 0.32 \qquad 22.0^{\circ}$ $0.12 \qquad 0.08 \qquad \omega_{OA} = 8 \qquad \frac{rad}{s} \qquad dS_{D} = \overline{CD} \ d\beta$ Thus $d\beta = \frac{\overline{OA}}{\overline{CD}} \frac{dS_{D}}{dS_{A}} \ d\theta \qquad d\beta = \frac{\overline{OA}}{\overline{CD}} \cos \theta \ \theta$ $So \ \omega_{CB} = \beta = \frac{0.32}{0.08 + 0.32 \cos 22^{\circ}} \cos 22^{\circ} \ (8) = 6.30 \ rad/s$

5/42 $y = 20 + 80 \sin \theta$, $\dot{y} = 80 \dot{\theta} \cos \theta$ $\dot{y} = 80 \dot{\theta} \cos \theta - 80 \dot{\theta}^2 \sin \theta$ For $\theta = 60^\circ$, $\dot{\theta} = 4 \frac{red}{5}$, $\ddot{\theta} = 8 \frac{rad}{5^2}$, $\ddot{y} = 80(8)(\frac{1}{2}) - 80(4)^2 \frac{\sqrt{3}}{2}$ 20 mm $\frac{3}{2}$ $\frac{3}{2}$ Thus $Q_B = \frac{789 \text{ mm/s}^2}{2} down$ $\frac{5/43}{V} \quad V = r\omega \quad \alpha = \dot{v} = \dot{r}\omega + r\dot{\omega} \quad \dot{\omega} = 0$ $\frac{V}{V} \quad But \quad \dot{r} = \frac{t}{2\pi/\omega} = \frac{tw}{2\pi} = \frac{tv}{2\pi r}$ $Thus \quad \alpha = \frac{tV}{2\pi r}\omega = \frac{t}{2\pi r^2}$

$$\frac{5/44}{C} \quad \tan \beta = \frac{0.2 \sin \theta}{0.4 - 0.2 \cos \theta}, \quad \tan \beta (2 - \cos \theta) = \sin \theta$$

$$\frac{C}{C} \quad \beta \quad \beta \sec^2 \beta (2 - \cos \theta) + \tan \beta (\theta \sin \theta) = \theta \cos \theta$$

$$\beta = \frac{\cos \theta - \sin \theta \tan \beta}{2 - \cos \theta} \cdot \theta \cos^2 \beta$$

$$= \frac{2\cos \theta - 1}{(2 - \cos \theta)^2} \cdot \theta \cos^2 \beta$$

$$For \omega = -\theta = 3 \frac{rad}{5}, \quad \theta = 45^\circ, \quad \beta = \tan^{-1} \frac{1/V_2}{2 - 1/V_2} = 28.7^\circ$$

$$\beta = \frac{2/V_2 - 1}{(2 - 1/V_2)^2} (-3) \cos^2 28.7^\circ = -0.572 \text{ rad/s}$$

$$So \omega_{06} = 0.572 \text{ rad/s} CCW$$

$$\begin{array}{c|c}
\hline
5/45 & \chi = 2\cos\theta \\
\dot{\chi} = -U_0 = -L\dot{\theta}\sin\theta \\
\dot{\omega} = \dot{\theta} = \frac{U_0}{L\sin\theta} \\
\text{where } L\sin\theta = y = \sqrt{L^2 - \chi^2} \\
\hline
\cos \omega = \frac{U_0}{\sqrt{L^2 - \chi^2}} \\
\dot{\alpha} = \dot{\theta} = \frac{U_0}{L}\frac{d}{dt}\csc\theta = \frac{U_0}{L}(-\cot\theta\csc\theta)\dot{\theta} \\
&= -\frac{U_0}{L}\frac{\chi}{y}\frac{L}{\dot{\theta}}\dot{\theta} = \frac{-\chi U_0^2}{y^2\sqrt{L^2 - \chi^2}} \\
&= \frac{-\chi U_0^2}{(L^2 - \chi^2)^{3/2}}
\end{array}$$

$$\frac{5/46}{\sin(\pi-\theta-\beta)} = \frac{l}{\sin(\theta+\beta)} = \frac{r}{\sin\beta}$$

$$\frac{\dot{\theta}=3}{\cos d/\sec} = \frac{r\sin(\theta+\beta)}{r\sin(\theta+\beta)} = l\sin\beta$$

$$r\sin(\theta+\beta) = l\sin\beta$$

$$l\cos\beta$$

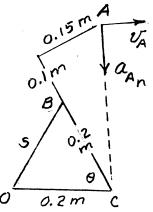
$$r\sin(\theta+\beta) = l\sin\beta$$

$$r\sin\beta$$

5/47 Belt velocity is the same for both pulleys

so $r_i \omega_i = r_2 \omega_2$ Thus $\dot{r}_i \omega_i + r_i \dot{\omega}_i = \dot{r}_2 \omega_2 + r_2 \dot{\omega}_2$ For $\dot{\omega}_i = 0$ & $\alpha_2 = \dot{\omega}_2$, we have $\alpha_2 = \dot{\alpha}_2 = \frac{\dot{r}_i \omega_i - \dot{r}_2 \omega_2}{r_2} = \frac{\dot{r}_i r_2 - r_i \dot{r}_2}{r_2^2} \omega_i$

5/48 Given $\dot{s} = 0.260 \text{ m/s}$ $S = 2(0.2) \sin \frac{\theta}{2}$ $\dot{s} = 0.2 \dot{\theta} \cos \frac{\theta}{2}$ For $\theta = 60^{\circ}$ $\dot{s} = 0.260 = 0.2 \dot{\theta} \cos \frac{60^{\circ}}{2}$ $\dot{\theta} = \omega_{AC} = \frac{0.260}{0.2\cos 30^{\circ}} = 1.501 \text{ rad/s}$ $AC = \sqrt{0.3^2 + 0.15^2} = 0.335 \text{ m}$ $A = AC \omega_{AC}^2$ $a = 0.335(1.501)^2 = 0.756 \text{ m/s}^2$

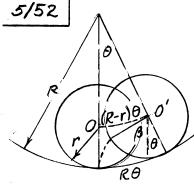


5/49 | Coordinates of Care

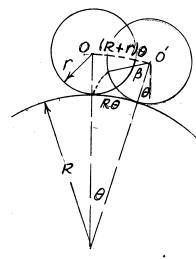
$$X = 3b \sin \frac{\theta}{2}, y = b \cos \frac{\theta}{2}$$
 $V_B = \frac{b}{2}b \sin \frac{\theta}{2}, y = -\frac{b}{2}b \sin \frac{\theta}{2}$
 $V_B = \frac{b}{2}b \cos \frac{\theta}{2}, y = -\frac{b}{2}b \sin \frac{\theta}{2}$
 $V_C = x^2 + y^2 = \frac{b^2\theta^2}{4}(9\cos^2\frac{\theta}{2} + [1-\cos^2\frac{\theta}{2}])$
 $V_C = \frac{b^2\theta^2}{4}(8\cos^2\frac{\theta}{2} + 1) = 2b^2\theta^2\cos^2\frac{\theta}{2} + \frac{1}{4}b^2\theta^2$
 $V_C = \frac{d}{dt}(2b\sin\frac{\theta}{2}) = -b\theta\cos\frac{\theta}{2}$
 $V_C = 2V_B^2 + \frac{1}{4}\frac{V_B^2}{\cos^2\theta_2}, V_C = \frac{V_B}{2}\sqrt{8 + \sec^2\frac{\theta}{2}}$

 $5/50 \quad Q_{A} = l\dot{\theta}^{2}, \quad Q_{A} = l\ddot{\theta}$ $5 = 2b \sin \frac{\theta}{2}$ $\dot{s} = k = b\dot{\theta} \cos \frac{\theta}{2}$ $0 = b\ddot{\theta} \cos \frac{\theta}{2} - \frac{b}{2}\dot{\theta}^{2} \sin \frac{\theta}{2}$ $\dot{\theta} = \frac{1}{2}\dot{\theta}^{2} \tan \frac{\theta}{2} = \frac{1}{2}\left(\frac{k}{b\cos \frac{\theta}{2}}\right)^{2} \tan \frac{\theta}{2} = \frac{k^{2}}{2b^{2}} \frac{\tan \frac{\theta}{2}}{\cos^{2}\frac{\theta}{2}}$ $Q_{A} = l\dot{\theta}^{2} e_{h} + l\ddot{\theta} e_{e} = \frac{k^{2}l}{b^{2}\cos^{2}\frac{\theta}{2}}\left(e_{h} + \frac{1}{2}\tan \frac{\theta}{2}e_{e}\right)$

5/51 $y = 2(0.2)\cos\theta$, $\dot{y} = -0.4\dot{\theta}\sin\theta$ $\dot{y} = -0.4\dot{\theta}\sin\theta - 0.4\dot{\theta}\cos\theta$ $y = -0.4\dot{\theta}\sin\theta - 0.4(\frac{\dot{y}}{-0.4\sin\theta})\cos\theta$ $y = -0.4\dot{\theta}\sin\theta - 0.4(\frac{\dot{y}}{-0.4\sin\theta})\cos\theta$ $y = -0.4\dot{\theta}\sin\theta - 0.4(\frac{\dot{y}}{-0.4\sin\theta})\cos\theta$ $\dot{y} = 0.2m$, $\theta = 60^{\circ}$, $\sin\theta = \frac{\sqrt{3}}{2}$, $\cos\theta = \frac{1}{2}$ $\dot{y} = 0.4m/s$, $\dot{y} = -0.1m/s^{2}$ $\dot{\theta} = -\frac{\dot{y}}{0.4\sin\theta} = -\frac{0.4}{0.4(\sqrt{3}/2)} = -1.155\frac{rad}{5}$, $\omega = 1.155\frac{rad}{5}$ ccw $\dot{\theta} = \frac{-\dot{y}}{0.4\sin\theta} = -\frac{\dot{y}^{2}\cos\theta}{0.16\sin^{3}\theta} = \frac{+0.1}{0.4(\sqrt{3}/2)} = \frac{0.4^{2}(1/2)}{0.16(\sqrt{3}\sqrt{3}/8)}$ $= 0.289 - 0.770 = -0.481 rad/s^{2}$, $\alpha = 0.481 rad/s^{2}$ ccw



 $V_0 = V = (R - r)\dot{\theta}$ $R\theta = r(\theta + \beta)$ $SO(R - r) = r\beta$ $\dot{\theta}(R - r) = r\beta$ $SO(F = r\dot{\beta}) = \theta \omega = \beta$ $V = r\omega \quad SO(a_2 = r\alpha)$ $(\beta = absolute \ angle)$



 $V_0 = V = (R+r)\theta$ $R\theta = r\beta \text{ so } \theta + \beta = (\frac{r+R}{r})\theta$ $\text{so } r(\theta + \beta) = (R+r)\theta$ $\text{where } \omega = (\beta + \theta)$ $\text{so } \frac{V = r\omega}{(\beta + \theta)} \text{ so } q = r\alpha$ $(\beta + \theta) = absolute \text{ angle}$

 $\omega_2 = 1.923 \, rad/s$

► 5/54 | $x = 8 \tan \theta$, $V_A = \dot{x} = 8 \dot{\theta} \sec^2 \theta$ x = A $a_A = \dot{x} = 8 \dot{\theta} \sec^2 \theta + 16 \dot{\theta}^2 \sec^2 \theta + \tan \theta$ $= 8 \dot{\theta} \sec^2 \theta + 16 \frac{V_A^2}{64 \sec^4 \theta} \sec^2 \theta + \tan \theta$ $= 8 \dot{\theta} \sec^2 \theta + \frac{V_A^2}{64 \sec^4 \theta} \sec^2 \theta + \tan \theta$ But for $\dot{x} = \cot \theta$. $= Q_A$, $V_A^2 = 2Q_A x$ But for $\dot{x} = \cot \theta$. $= Q_A \cos \theta$ Substitute $Q_A = 8 \dot{\theta} \sec^2 \theta + \frac{Q_A x}{2} \sin \theta \cos \theta$ Substitute $Q_A = 4 \sin/\sec^2$, $\sec \theta = 5/4$, $\cos \theta = 4/5$ $\sin \theta = 3/5$ for x = 6 in. $4 = 8 \dot{\theta} (5/4)^2 + \frac{4(6)}{2} \frac{3}{5} \frac{4}{5}$, $\dot{\theta} = -0.1408 \text{ rad/sec}^2$ So $\alpha = 0.1408 \text{ rad/sec}^2$ CCW ►5/55 $\theta = \theta \sin 2\pi t$, $\dot{\theta} = 2\pi \theta_0 \cos 2\pi t$, $\ddot{\theta} = -4\pi^2 \theta_0 \sin 2\pi t$ $\theta = \pi/12$ when $\theta = 0$, t = 1/25 \$\delta \delta = \text{2\pi \theta} = \text{17\theta} \text{6} = 0 \\

\[
\begin{align*}
& \theta = \frac{\pi}{12}, \tau = 1/45 \delta \delta = 0, \delta = -4\pi^2\theta = -\pi^3/3 \text{ rad/s}^2 \\
& \theta = \frac{\pi}{12}, \tau = 1/45 \delta \delta = 0, \delta = -4\pi^2\theta = -\pi^3/3 \text{ rad/s}^2 \\
& \theta = \frac{\pi}{12}, \tau = 1/45 \delta \delta = 0, \delta \delta = -\pi^3/3 \text{ rad/s}^2 \\
& \theta = \frac{\pi}{12}, \tau = 1/45 \delta \delta = 0, \delta \delta \delta \delta \delta = -\pi^3/3 \text{ rad/s}^2 \\
& \theta = \frac{\pi}{12}, \tau = 1/45 \delta \d

(b) $\theta = \tilde{n}/|_{12}$, $b/\sin\beta = 1/\sin\frac{\pi}{12}$, $\beta = \sin^{-1}(\frac{0.14}{0.1}\sin\frac{\pi}{12}) = 21.24^{\circ}$ $\dot{y} = 0$ $\dot{y} = b\cos\theta + 2\cos\beta = 0.14\cos\frac{\pi}{12} + 0.1\cos21.24^{\circ} = 0.2284$ m $\dot{\theta} = 0$ $\ddot{y}(0.14\cos\frac{\pi}{12} - 0.2284) = 0 + 0 + 0.2284(0.14)(-\frac{\pi^{3}}{3})\sin\frac{\pi}{12} + 0$ $\ddot{y}(-0.09320) = -0.08555$, $\ddot{y} = 0.918$ m/s² (down) (a)
$$\frac{V_A=4}{V_{A/0}=8} \frac{V_O=4}{ff/sec}$$
 $W = \frac{8}{10/12} = 9.6 \frac{rad}{sec}$, $N = 9.6 \frac{60}{2\pi} = 91.7 \frac{rev}{min}$ CCW

(b)
$$\frac{U_0=4}{\omega}$$
 $U=0$, $\omega=\frac{4}{10/12}=4.8\frac{rad}{sec}$, $N=45.8\frac{rev}{min}$

$$CCW$$

(c)
$$\frac{U_0=4}{V_A=8} \frac{V_{A|0}=4}{V_A=8} \frac{4}{5} = 4.8 \frac{rod}{5}, N=45.8 \frac{rov}{min} CW$$

$$\frac{5/58}{R} = \frac{107257j \text{ km/h}}{R\Omega} = \frac{107257j \text{ km/h}}{R\Omega} = \frac{6371(10^3)[7.292(10^{-5})]}{R\Omega} = \frac{465 \frac{\text{m}}{\text{s}}(3.6 \frac{\text{km/h}}{\text{m/s}})}{1672 \text{ km/h}}$$

$$\frac{\nu_{A}}{\nu_{B}} = \frac{\nu_{o} + \nu_{A|o}}{\nu_{b}} = \frac{-1672i}{107257j} + \frac{107257j}{1072j} = \frac{105585j}{105585j} \frac{km/h}{h}$$

$$\frac{\nu_{C}}{\nu_{C}} = \frac{\nu_{O}}{\nu_{O}} + \frac{\nu_{C/O}}{\nu_{C/O}} = \frac{1672i}{107257j} + \frac{107257j}{108929j} + \frac{108929j}{108929j} \frac{km/h}{h}$$

$$\frac{\nu_{D}}{\nu_{D}} = \frac{\nu_{O}}{\nu_{O}} + \frac{\nu_{D/O}}{\nu_{D/O}} = \frac{(07257 + 1672)j}{108929j} = \frac{108929j}{108929j} \frac{km/h}{h}$$

5/59
$$V_{B/A} = AB \omega$$
, $V_{C/D} = CD \omega$
Therefore $V_{C/D} = \frac{CD}{AB} V_{B/A} = \frac{50}{80} 0.926 = 0.579 \text{ m/s}$

$$5/60$$
 $|V_0| = |V_{A/0}| = r\omega = 12 \cos 45^\circ = 8.49 \text{ m/s}$

$$V_{A|o} = r\omega$$

$$A = \frac{8.49}{0.300} = \frac{28.3 \text{ rad/s}}{28.3 \text{ rad/s}}$$

$$V_{A|o} = r\omega$$

$$V_{A|o}$$

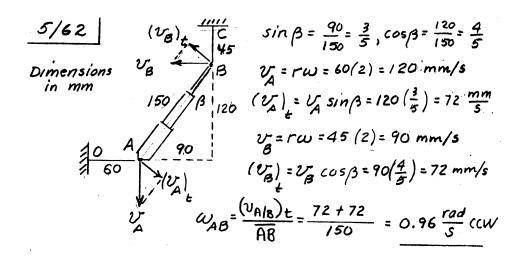
5/61
$$V_A = V_B + V_{A/B}$$
, $V_{A/B} = \overline{AB} cu_{AB} = 20(4) = 80 \frac{mm}{5}$

$$V_B = 40 \text{ mm/5}$$

$$V_A = \sqrt{(80 \sin 45^\circ)^2 + (80 \cos 45^\circ - 40)^2}$$

$$V_A = \sqrt{3470} = 58.9 \text{ mm/5}$$

$$V_{A/B} = 80 \text{ mm/5}$$



$$\begin{array}{c|c}
\hline
5/63 \\
\hline
V_{C/B} = 1.2j \text{ m/s} \\
\hline
0.4m \\
\hline
0.4m \\
V_A = 2i \text{ m/s}
\end{array}$$

$$U_{G} = 2.6 i + 0.6 j$$
 m/s

$$\frac{5/65}{90^{2} = 180^{2} + 130^{2} - 2(180)(130)\cos\theta}$$

$$\frac{130}{\sin\beta} = \frac{90}{\sin 28.3^{\circ}}, \beta = 43.2^{\circ}$$

$$\frac{130}{\sin\beta} = \frac{90}{\sin 28.3^{\circ}}, \beta = 43.2^{\circ}$$

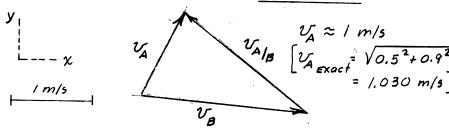
$$\frac{180 \text{ mm}}{300} = \frac{90}{\sin 28.3^{\circ}}, \beta = 43.2^{\circ}$$

$$\frac{180 \text{ mm}}{300} = \frac{90}{\sin 28.3^{\circ}}, \beta = 43.2^{\circ}$$

$$\frac{190}{300} = \frac{90}{300} = \frac{90$$

5/67 $V_A = V_B + V_{A/B}$ where $V_B = 2i - 0.3j$ m/s $V_{A/B} = CU \times I_{A/B} = 3k \times (0.4i + 0.5j) = 1.2j - 1.5i$ m/s

So $V_A = 2i - 0.3j + 1.2j - 1.5i = 0.5i + 0.9j$ m/s



$$\beta = \sin^{-1} \frac{0.5 - 0.5 \sin 30^{\circ}}{1.2}$$

$$= 12.02^{\circ}$$
A
$$\frac{30^{\circ}}{1.2} = 3 \text{ m/s}$$

$$\bar{\nu}_{B} = \bar{\nu}_{A} + \bar{\nu}_{B|A} = \nu_{A} + \bar{\omega} \times \bar{\nu}_{B|A}$$

$$v_{B}(\sin 30^{\circ}i - \cos 30^{\circ}j) = 3i + \omega_{K} \times 1.2(-\cos \beta i + \sin \beta j)$$

= $3i + \omega_{K} \times 1.2(-\cos 12.02^{\circ}i + \sin 12.02^{\circ}j)$
= $3i - 1.174\omega_{j} - 0.250\omega_{i}$

$$\frac{i}{i}: \frac{1}{2}v_{8} = 3 - 0.250 \omega$$

$$\frac{1}{i}: -\frac{\sqrt{3}}{2}v_{8} = -1.174 \omega$$

$$\omega = 3.23 \text{ rad/s}$$

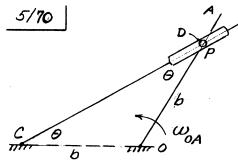
$$\begin{array}{c|c}
5/69 & \underline{U}_{B} = \underline{U}_{A} + \underline{U}_{B/A} \\
\underline{U}_{A} = 4 & ft/sec \\
\underline{U}_{B} = 4 & ft/sec
\end{array}$$

$$\begin{array}{c|c}
\underline{U}_{B} = 4 & ft/sec \\
\underline{U}_{B} = 20'' & 70''''' \\
\underline{U}_{B} = 4 & ft/sec & 60'
\end{array}$$

$$\begin{array}{c|c}
\underline{U}_{B} = \frac{2}{\omega s 30''} = 2.31 & ft/sec & A
\end{array}$$

$$\begin{array}{c|c}
\underline{U}_{B} = \frac{2}{\omega s 30''} = 2.31 & ft/sec & CCW
\end{array}$$

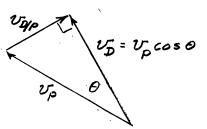
$$\begin{array}{c|c}
\underline{U}_{B} = \frac{2.31}{|0/12|} = 2.77 & rad/sec & CCW
\end{array}$$



$$U_D = \overline{CD} \omega_{CB} = 2b \cos \theta \ \omega_{CB}$$

So $2b \cos \theta \ \omega_{CB} = b \omega_{OA} \cos \theta$

Thus $\omega_{CB} = \frac{1}{2} \omega_{OA}$



5/71
$$\omega_{AB} = 3 \text{ rad/sec}$$
 $S = U_A + U_{B/A}$, $\omega_B = \frac{U_B}{BC}$
 $S'' \downarrow \theta$
 S''

$$V_{B} = V_{A} + V_{B/A}, \quad W_{BC} = \frac{V_{B}}{BC}$$

$$V_{B/A} = AB \, W_{AB}$$

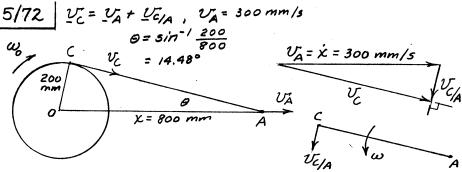
$$= 5(3) = 15 \text{ in./sec}$$

$$\theta = \cos^{-1} \frac{3}{5}$$

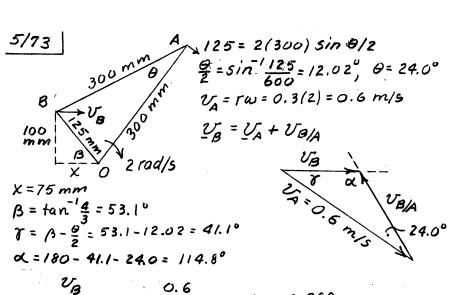
$$V_{B} = V_{B/A} \cos \theta$$

$$= 15(3/5) = 9 \text{ in./sec}$$

$$W_{BC} = 9/3 = 3 \text{ rad/sec CV}$$

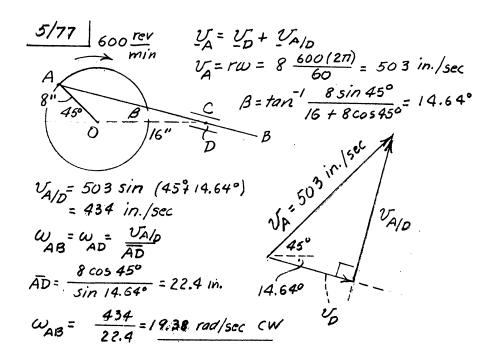


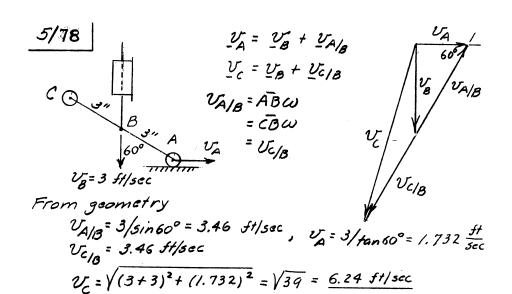
$$V_{c} = 300 \cos 14.48^{\circ}$$
 $= 300(0.9682) = 290 \text{ mm/s}$
 $V_{c/A} = 300 \sin 14.48^{\circ} = 300/4 = 75 \text{ mm/s}$
 $CA = 800 \cos 14.48^{\circ} = 775 \text{ mm}$
 $W_{AB} = V_{c/A}/CA = 75/775 = 0.0968 \text{ rad/s} \text{ CCW}$
 $W_{o} = V_{c}/C_{o} = 290/200 = 1.452 \text{ rad/s} \text{ CW}$

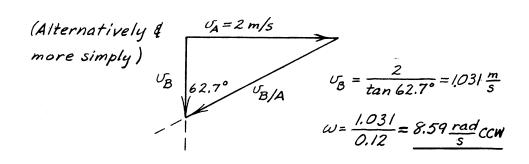


$$\frac{v_B}{\sin 24.0^\circ} = \frac{0.6}{\sin 114.8}, \quad v_B = 0.269 \text{ m/s}$$

(b)
$$v_A = v_B = z_{rw}$$
 (right)
 $\omega_{BC} = \frac{v_B}{BC} = \frac{z_{rw}}{r} = z_w c_{cw}$







5/81 CA = 0.12i +0.16j m TOB = 0.12j m, TBA = 0.24i + 0.04j m V= WX TCA $\begin{array}{lll}
 & B & = \omega_{AC} \times (0.12 i + 0.16 j) \\
 & 120 & 5 & = 0.12 \omega_{AC} j - 0.16 \omega_{DC} i
\end{array}$ 160 O mm VB= WOBX TOB= 0.5K x 0.12j 120 mm mm =-0.06i m/s UA/13 = WABX [BA = WAB KX (0.24i + 0.04j) = 0.24 WAB j - 0.04 WAB i VA = VB + VA/B, 50 0.12 WAC j - 0.16 WAC i = -0.06 i

+0.24 WAB j - 0.04 WAB L

Equate coefficients A get

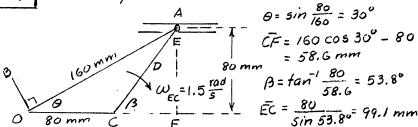
0.16 WAC - 0.04 WAB = 0.06 0.12 WAC - 0.24 WAB = 0

solve & get

WAB = 0.214 k rod/s, WCA = 0.429 k rad/s

5/83
$$\omega_{AB}$$
 ω_{AB} ω_{AB

5/84 | Let E be point on member D coincident with A



$$V_{A} = V_{E} + V_{A/E}$$

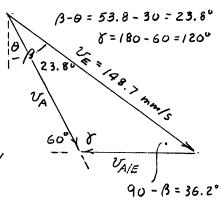
$$V_{E} = 99.1(1.5) = 148.7 \frac{mm}{5}$$

$$\frac{V_A}{\sin 36.2^{\circ}} = \frac{148.7}{\sin 120^{\circ}}$$

$$V_A = 148.7 \frac{0.591}{0.866} = 101.4 \frac{mm}{5}$$

$$\omega_{AOB} = \frac{101.4}{160} = \frac{0.634 \, rad/s}{1000} \, \text{CW}$$

Alternatively, draw vector triangle to scale 4 measure $V_A \approx 101 \text{ mm/s}$. Etc.



$$V_{D} = V_{D} + V_{D}/\rho$$

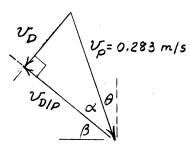
$$V_{P} = 0.1\sqrt{2}(2) = 0.283 \text{ m/s}$$

$$V_{D} = 0.283 \text{ sin } 34.2^{\circ}$$

$$= 0.1591 \text{ m/s}$$

$$W_{2} = V_{D}/2 = 0.1591/0.0827$$

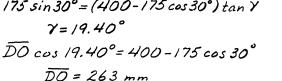
$$W_{2} = 1.923 \text{ rad/s}$$



 $\alpha = 90 - \theta - \beta$ = $90 - (20 + 35.8) = 34.2^{\circ}$

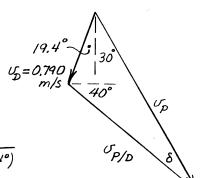
5/86 Let D be a point on OA coincident with P. $\underline{\underline{U}}_{p} = \underline{\underline{U}}_{D} + \underline{\underline{U}}_{p/D}$ where $\underline{\underline{U}}_{D}$ is $\underline{\underline{L}}$ to $\underline{\underline{OD}}$

From triangle BOD, 175 sin 30° = (400-175 cos 30°) tan Y 7=19.40°



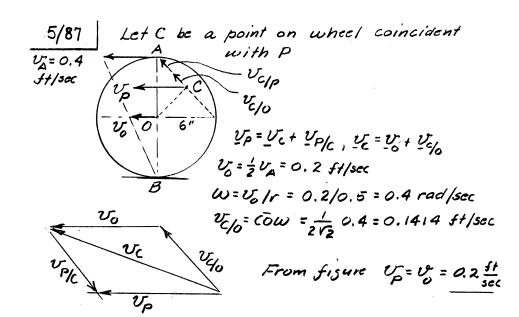
$$U_D = \overline{DO} \omega_{DO} = 263(3) = 790 \text{ mm/s} = 0.790 \text{ m/s}$$

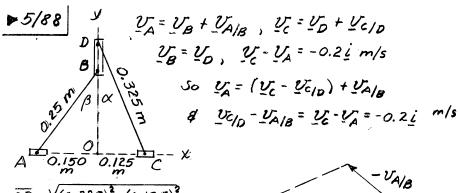
δ+30°+90°+40°=180°, δ = 20°



Law of sines: 5in(40°+90°-19.4°) $=\frac{0.790}{\sin 20^{\circ}}$, $\sigma_p = 2.16 \text{ m/s}$

$$U_{\rm C} = 2U_{\rm p} = \frac{4.33 \, m/s}{}$$





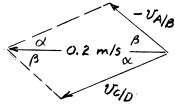
$$\overline{OD} = \sqrt{(0.325)^2 - (0.125)^2}$$

= 0.3m

$$\overline{OB} = \sqrt{(0.25)^2 - (0.15)^2}$$
= 0.2 m

Sin
$$\alpha = 0.125/0.325 = 5/13$$

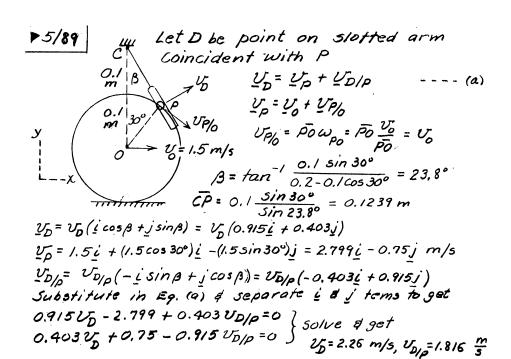
 $\cos \alpha = 0.3/0.325 = 12/13$
 $\sin \beta = 0.150/0.250 = 3/5$
 $\cos \beta = 0.2/0.25 = 4/5$



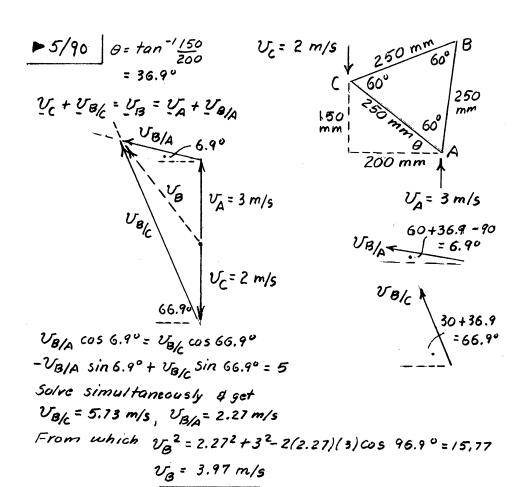
 $U_{C/D} \cos \alpha + U_{A/B} \cos \beta = 0.2$ $U_{C/D} \sin \alpha - U_{A/B} \sin \beta = 0$ $50/ve \notin get U_{C/D} = \frac{39}{280} = 0.1393$ m/s

$$\frac{V - V_D - V_C - V_{C/D}}{V - V_D} = \frac{39}{5} \left[-\frac{39}{280} \right] \left(-\frac{1}{5} \cos \alpha - \frac{1}{5} \sin \alpha \right)$$

$$50 \ V = \frac{39}{280} \frac{5}{13} = \frac{3}{5} = \frac{0.0536}{5} \frac{\text{m/s}}{5}$$



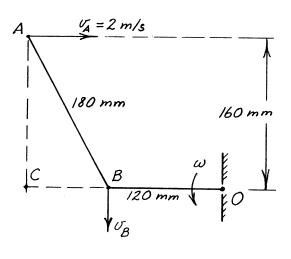
Thus $\omega = \omega_{CD} = \frac{2.26}{0.1239} = 18.22 \text{ rad/s ccw}$

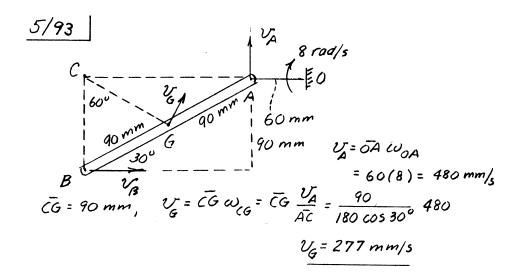


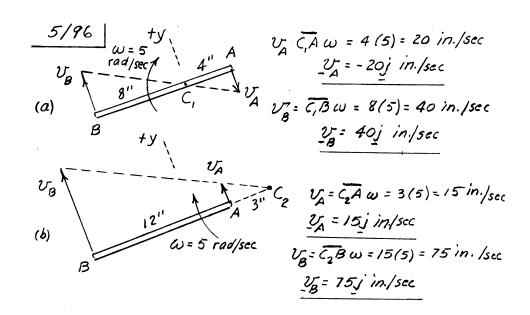
$$\omega = V_A / \overline{AC}$$

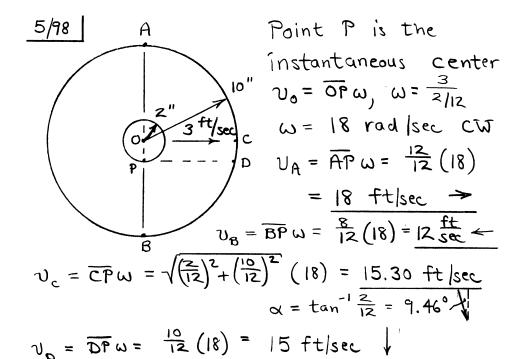
$$\frac{5/92}{CB} = \sqrt{180^2 - 160^2}$$
= 82.5 mm
$$\frac{U_B}{CB} = \frac{U_A}{AC}, U_B = \frac{82.5}{160}2$$
= 1.031 m/s
$$\omega_{0B} = \omega = \frac{1.031}{0.120}$$

= 8.59 rad/s

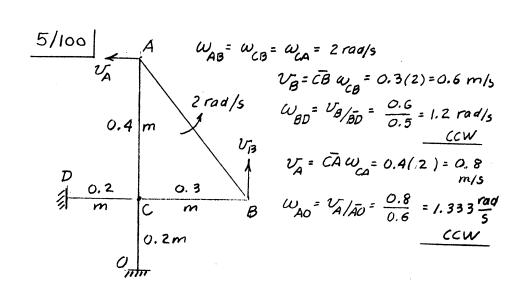




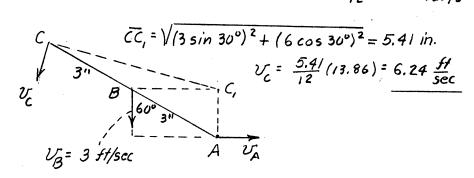




 $\frac{5/99}{v_0 = 0.75} = \frac{0.1414 \text{ m/s}}{0.75 \text{ mm}} = \frac{0.1414 \text{ m/s}}{0.75 \text{ mm}}$



$$5/101$$
 $U_{C} = \overline{CC}$, ω_{AC} , $\omega_{AC} = \omega_{AB} = U_{B}/\overline{BC}$, $= \frac{3}{12} \sin 60^{\circ} = 13.86$



5/102

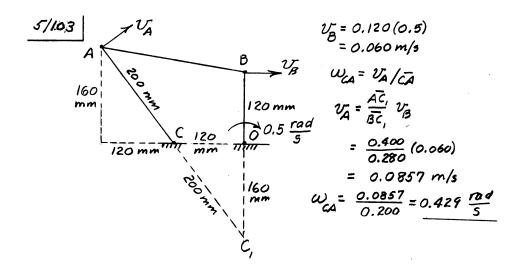
 $\omega = \sigma / \overline{OC}$, $\sigma = \frac{q}{12} \cdot 20.9 = 15.71$ ft/sec

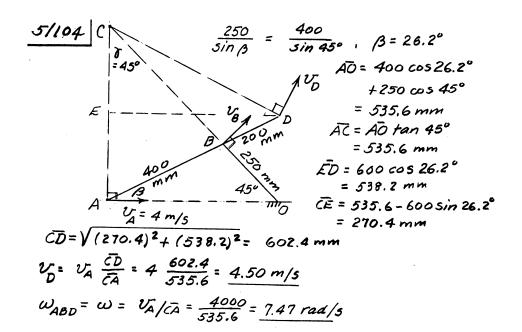
or v = 10.71 mi/hr

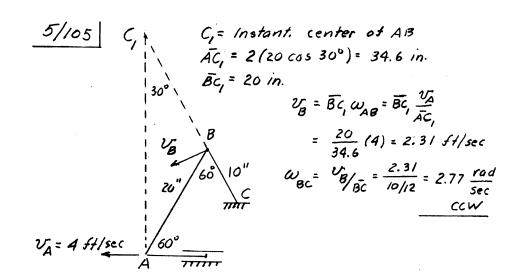
 $v_s = \frac{4}{9}v = \frac{4}{9}(15.71), v_s = 6.98 \text{ ft/sec}$

$$O \qquad U \\ \omega = \frac{2\pi N}{60}$$

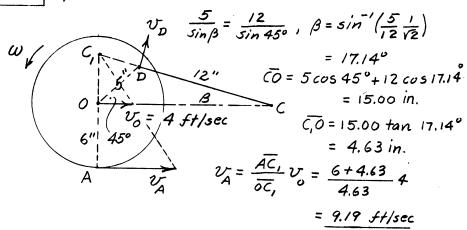
$$C \neq U \\ \omega = \frac{20.9 \frac{\text{rad}}{\text{sec}}}{\text{sec}}$$







5/106 C = instantaneous center



$$\frac{5/107}{AC/BC} = \frac{1.2}{1.8} 4 \overline{AC} + \overline{BC} = 200 \text{ mm}$$

$$\frac{50 \overline{AC}}{80 \text{ mm}} = \frac{80 \text{ mm}}{0\overline{C}} = 40 \text{ mm}$$

$$\frac{4}{AC} = \frac{1.2}{5} = \frac{1.2}{0.08} = \frac{1.5}{15 \text{ rad/s}}$$

$$\frac{80 \text{ mm}}{AC} = \frac{1.2}{0.08} = \frac{1.5}{15 \text{ rad/s}}$$

$$\frac{15 \text{ rad/s}}{\sqrt{2} = 0.040 (15)} = 0.6 \frac{\text{m}}{5}$$

$$\frac{15 \text{ rad/s}}{\sqrt{2} = 126.5 \text{ mm}}$$

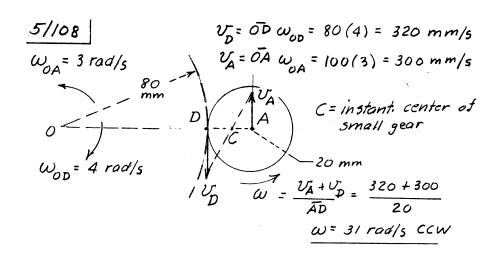
$$\frac{15 \text{ rad/s}}{\sqrt{2} = 126.5 \text{ mm}}$$

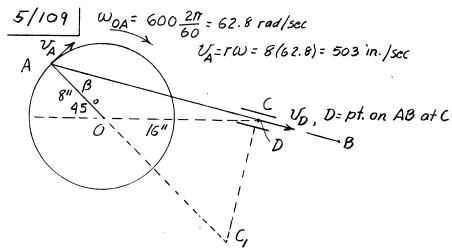
$$\frac{16 \text{ rad/s}}{\sqrt{2} = 1.8 \text{ m/s}}$$

$$\frac{16 \text{ rad/s}}{\sqrt{2} = 126.5 \text{ mm}}$$

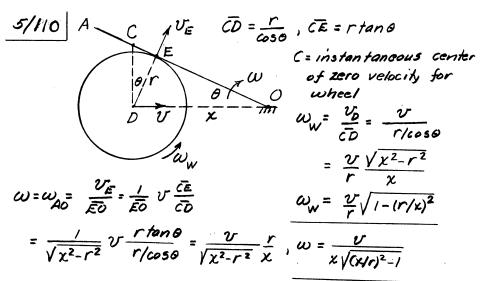
$$\frac{16 \text{ rad/s}}{\sqrt{2} = 1.8 \text{ m/s}}$$

$$\frac{16 \text{ rad/s}}{\sqrt{2} = 1.8 \text{ rad/s}}$$





$$\overline{AD} = \sqrt{8^2 + 16^2 - 2(8)(16)\cos 135^\circ} = 22.4 \text{ in.}$$
 $16/\sin \beta = 22.4/\sin 135^\circ$, $\beta = 30.4^\circ$
 $\overline{AC}_1 = 22.4/\cos 30.4^\circ = 25.9 \text{ in.}$
 $\omega_{AB} = \omega_{AD} = \omega_{AC_1} = \frac{v_A}{AC_1} = \frac{503}{25.9} = 19.38 \text{ rad/sec. CW}$

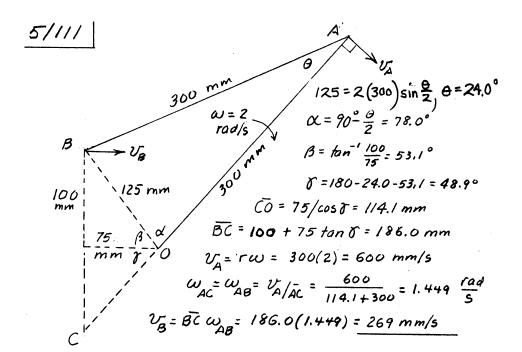


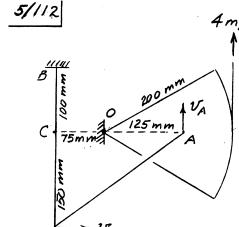
$$\omega = \omega_{AO} = \frac{v_E}{EO} = \frac{1}{EO} v \frac{CE}{CO}$$

$$= \frac{1}{EO} v \frac{r ton \theta}{EO} = v r$$

$$\omega_{W} = \frac{v_{b}}{c\overline{c}} = \frac{v}{r/\cos \theta}$$
$$= \frac{v}{r} \frac{\sqrt{x^{2}-r^{2}}}{x}$$
$$\omega = v \sqrt{\sqrt{x^{2}-r^{2}}}$$

$$\omega = \frac{v}{x\sqrt{(x/r)^2-1}}$$





C=Instantaneous

center of zero

velocity for AD.

$$V_A = \frac{125}{200}(4) = 2.5 \text{ m/s}$$

$$W_{AD} = \frac{V_A}{\overline{A}C} = \frac{2.5}{0.200} = 12.5 \frac{\text{rad}}{\text{s}}$$

$$V = \overline{CD}W_{CD} = \overline{CD}W_{AD}$$

$$= 0.150 (12.5)$$

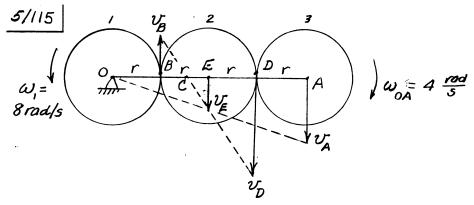
$$= 1.875 \text{ m/s}$$

$$\omega_{BD} = \frac{U_D}{BD} = \frac{1.875}{0.25} = 7.5 \text{ rad/s}$$

5/114 C is the instantaneous

center of zero velocity for DBA

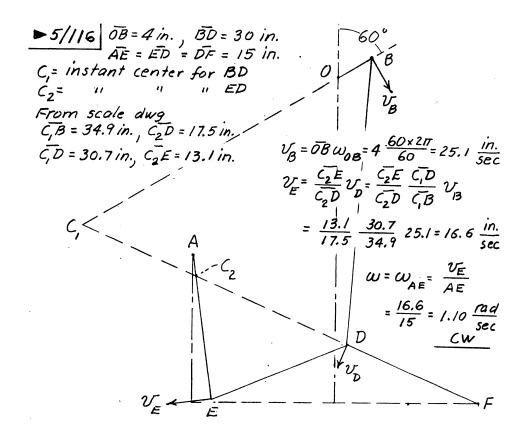
From geometry, $\overline{AC} = \frac{5}{3}(120) = 200 \text{ mm}$ $\overline{BC} = 160 \text{ mm}$ $\overline{DC} = \sqrt{60^2 + 160^2}$ = 170.9 mm $0 = \sin^{-1}\frac{120}{200} = 36.9^{\circ}$ $0 = \tan^{-1}\frac{60}{160} = 20.6^{\circ}$ $0 = 20.6^{\circ}$

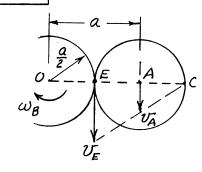


Let B be contact point common to gears 1 \$2

" D " " " " " " " " " " " " gears 2 \$3

Point C is instantaneous center of zero velocity
for gear 2. By similar triangles, U = 3(8r) = 24r $U_g = rw_1 = 8r$ $V_A = \overline{OA} w_{OA} = 4r(4) = 16r$ $V_E = 2rw_{OA} = 8r$ $w_3 = \frac{v_{OA}}{\overline{OA}} = \frac{24r - 16r}{r} = 8 \text{ rad/s ccw}$





(a)
$$V_A = \omega_{OA} a$$

 $V_E = 2V_A = 2a \omega_{OA}$

$$\omega_{B} = \frac{v_{E}}{a/2} = \frac{2a \, \omega_{oA}}{a/2} = 4(90)$$

$$= \frac{360 \, \text{rev/min}}{a}$$

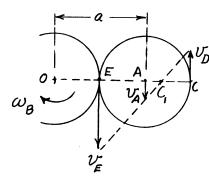
(b)
$$V_D = o\bar{c} \omega_D = \frac{3a}{2} 80 = 120a$$

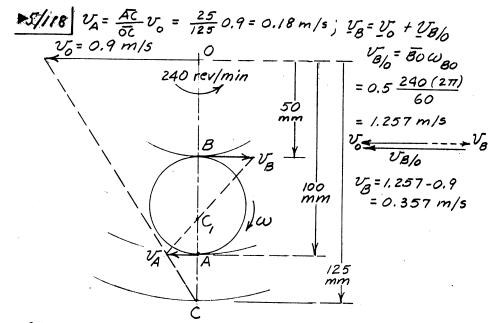
$$\frac{V_A + V_D}{a} = \frac{V_E - V_A}{a}, V_E = V_D + 2V_A$$

$$\frac{V_D}{a} = \frac{V_E - V_A}{a}, V_E = V_D + 2V_A$$

$$= 300a$$

$$\omega_{OE} = \omega_B = \frac{v_E}{a/2} = \frac{300a}{a/2} = 600 \frac{rev}{min}$$





$$\frac{v_B}{BC_1} = \frac{v_A + v_B}{AB} = \omega$$
, $\omega = \frac{0.18 + 0.357}{0.05} = \frac{10.73 \text{ rad/s CW}}{0.05}$

$$\frac{5/119}{Scalar - geometric} Q_{A/C} + (Q_{A/C})_{n} + (Q_{A/C})_{t}$$

$$\frac{Scalar - geometric}{(Q_{A/C})_{n} = \overline{AC} \omega_{AC}^{2} = 0.5(4^{2}) = 8 \text{ m/s}^{2}}$$

$$(Q_{A/C})_{t} = \overline{AC} \alpha_{AC} = 0.5(12) = 6 \text{ m/s}^{2} \qquad (Q_{A/C})_{t}$$

$$Q_{A/C} = \overline{AC} \alpha_{AC} = 0.5(12) = 6 \text{ m/s}^{2} \qquad (Q_{A/C})_{n}$$

$$Q_{A/C} = \sqrt{(5 + \frac{3}{5}8 - \frac{4}{5}6)^{2} + (\frac{4}{5}8 + \frac{3}{5}6)^{2}} = 11.18 \text{ m/s}^{2}$$

Vector - algebraic

$$(a_{A/c})_n = \omega \times (\omega \times r) = -4k \times (-4k \times [0.4i + 0.3j])$$

= -6.4i - 4.8j m/s²

$$(Q_{A/C})_{i} = \alpha \times \Gamma = 12 \times \times (0.4 i + 0.3 j) = 4.8 j - 3.6 i m/s^{2}$$

 $Q_{C} = -5 j m/s^{2}$

Substitute, equate i & j coefficients, & get
$$(Q_A)_X = -10 \text{ m/s}^2$$
, $(Q_A)_Y = -5 \text{ m/s}^2$
So $Q_A = \sqrt{(-10)^2 + (-5)^2} = 11.18 \text{ m/s}^2$

$$\frac{5/120}{(a_{A/0})_n} = \frac{Q_0 + (a_{A/0})_n + (a_{A/0})_t}{(a_{A/0})_n} = \frac{Q_0 + (a_{A/0})_n}{(a_{A/0})_t} = \frac{Q_0 + (a_{A/0})_n}{(a_{A/0})_t} = \frac{Q_0 + (a_{A/0})_n}{(a_{A/0})_t} = \frac{Q_0 + (a_{A/0})_n}{(a_{A/0})_n} = \frac{Q_0 + (a_{A/0})_n}{(a_{A/0})_n} = \frac{Q_0 + (a_{A/0})_n}{(a_{A/0})_n} = \frac{Q_0 + (a_{A/0})_n}{(a_{A/0})_n} = \frac{Q_0 + (a_{A/0})_t}{(a_{A/0})_n} = \frac{Q_0 + (a_{A/0})_t}{(a_{A/0})_t} = \frac{Q_0 + (a_{A/0})_t}{(a_{A$$

(b)
$$\theta = 90^{\circ}$$

$$Q_{2} = 3 \text{ m/s}^{2}$$

$$Q_{2} = \sqrt{3^{2} + 3.2^{2}}$$

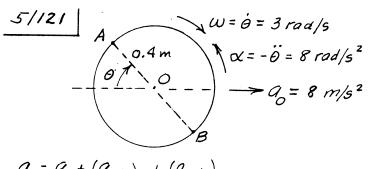
$$Q_{3} = \sqrt{3^{2} + 3.2^{2}}$$

$$Q_{4} = \sqrt{3^{2} + 3.2^{2}}$$

$$Q_{5} = 4.39 \text{ m/s}^{2}$$

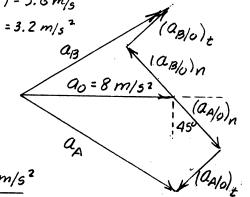
$$Q_{6} = 3 \text{ m/s}^{2} (Q_{6})_{n} = 3.2 \text{ m/s}^{2}$$

$$Q_{7} = 3 + 3.2 = 6.2 \text{ m/s}^{2}$$



$$\begin{array}{c}
Q_{A} = Q_{0} + (Q_{A/0})_{n} + (Q_{A/0})_{t} \\
(Q_{A/0})_{n} = \overline{A_{0}} \omega^{2} = 0.4 (3^{2}) = 3.6 \, \text{m/s}^{2} \\
(Q_{A/0})_{t} = \overline{A_{0}} \omega = 0.4 (8) = 3.2 \, \text{m/s}^{2} \\
Q_{B} = Q_{0} + (Q_{B/0})_{n} + (Q_{B/0})_{t} \\
(Q_{B/0})_{n} = 3.6 \, \text{m/s}^{2} \\
(Q_{A/0})_{t} = 3.2 \, \text{m/s}^{2}
\end{array}$$

$$\begin{array}{c}
Q_{A} = Q_{0} + Q_{$$



$$\frac{5/122}{p} = \frac{6.673(10^{-11})[5.976 \cdot 10^{24} \cdot 333000]}{[149.6(10^{9})]^{2}}$$

$$= \frac{6.673(10^{-11})[5.976 \cdot 10^{24} \cdot 333000]}{[149.6(10^{9})]^{2}}$$

$$= 0.00593 \text{ m/s}^{2} (4)$$

$$R\omega^{2} = 6371(10^{3})[7.292(10^{-5})]^{2}$$

$$= 0.0339 \text{ m/s}^{2} (3)$$

$$\alpha_{B} = \alpha_{0} + \alpha_{B/0} = -0.00593 \cdot 1 + 0.0339 \cdot 1$$

$$= 0.0279 \cdot 1 \text{ m/s}^{2}$$

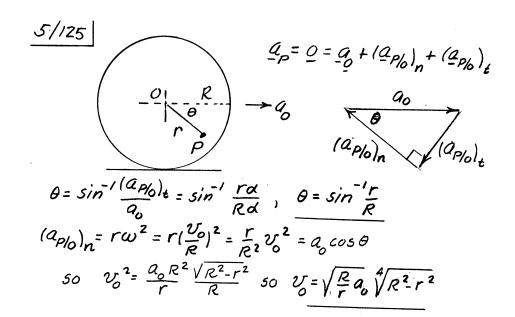
$$\frac{1}{4}a_{c} = a_{B} + a_{c/3} = -0.1 + 3(0.05) = 0.05 \text{ m/s}^{2} \text{ down}$$

 $\frac{1}{4}a_{p} = 0 = a_{B} + a_{P/B} = -0.1 + b(0.05), b = 2 \text{ m}$

5/124 In the coordinates shown, the no-slip

Kinematic constraints are $v_0 = -r\omega$, $q_0 = -r\omega$.

So $\omega = -\frac{y_0}{r} = -\frac{3}{0.4} = -7.5 \text{ rad/s}$ $\alpha = -\frac{q_0}{r} = -\frac{5}{0.4} = 12.5 \text{ rod/s}^2$ $v_0 = v_0 + v_0 = v_0 + w_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + w_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + w_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + v_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + v_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + v_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + v_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + v_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + v_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + v_0 \times v_0$ $v_0 = v_0 + v_0 = v_0 + v_0 \times v_0$ $v_0 = v_0 + v$



5/126

$$(Q_{A/B})_{t} = \frac{2.7}{\sqrt{2}} m/s^{2}$$

$$= \frac{2.7}{\sqrt{2}} \frac{1}{0.15\sqrt{2}}$$

$$(Q_{A/B})_{t} = AB \omega^{2}; \quad \omega^{2} = \frac{2.7}{\sqrt{2}} \frac{1}{0.15\sqrt{2}}$$

$$= \frac{2.7}{\sqrt{2}} \frac{1}{0.15\sqrt{2}} = \frac{9 \text{ rad/s}^{2}}{0.15\sqrt{2}} \quad \omega = \frac{3 \text{ rad/s}}{3}$$

$$= \frac{2.7}{\sqrt{2}} \frac{1}{0.15\sqrt{2}} = \frac{9 \text{ rad/s}^{2}}{0.15\sqrt{2}} \quad \omega = \frac{3 \text{ rad/s}}{3}$$

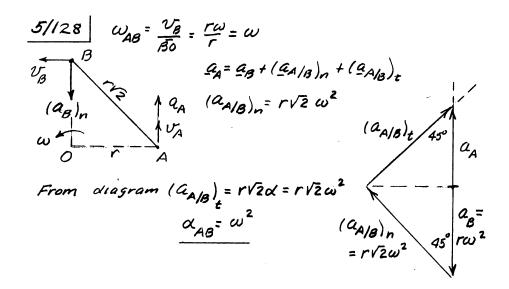
$$= \frac{3 \text{ rad/s}}{3 \text{ rad/s}}$$

5/127 $v_0 = \frac{10}{3.6} = 2.78 \text{ m/s}, \quad \omega = \frac{2.78}{0.300} = 9.26 \text{ rad/s}$ A $v_0^2 = 205, \quad q_0 = \frac{v_0^2}{25} = \frac{(60/3.6)^2}{2(40)} = 3.47 \text{ m/s}^2$ $\omega = q_0/r = 3.47/0.300 = 11.57 \frac{\text{rad}}{52}$ $\alpha = q_0/r = 3.47/0.300 = 11.57 \frac{\text{rad}}{52}$

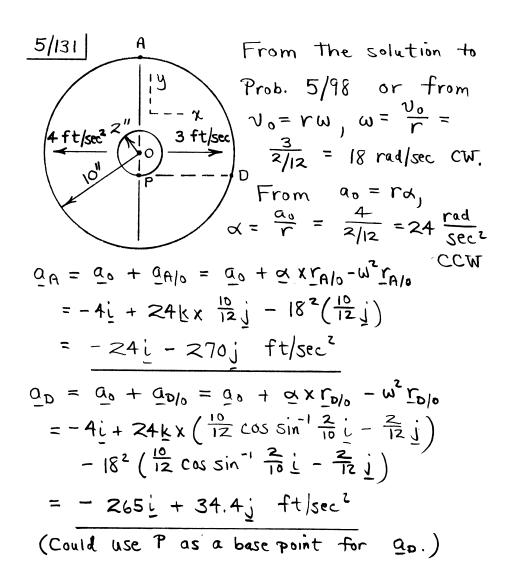
$$(a_{A/o})_n$$

$$a_A = \sqrt{(3.47 + 3.47)^2 + (25.72)^2} = 26.6 \text{ m/s}^2$$

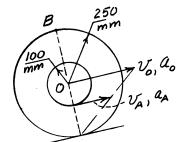
$$(a_{A/o})_t$$

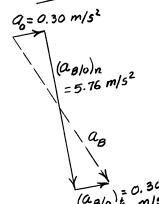


5/130 $V_{A} = V_{B} + W_{AB} \times I_{A/B}$ A = 0.3 m $V_{A}i = 0.4(4)(-i) + W_{AB}i_{X} \times (-0.3i + 0.4i)$ $V_{A}i = -1.6j - 0.3 W_{AB}i_{Y} - 0.4 W_{AB}i_{X}$ 0.4 m 0.5 m $V_{A}i = -1.6j - 0.3 W_{AB}i_{Y} - 0.4 W_{AB}i_{X}$ 0.4 m 0.4 m 0.5 m $V_{A}i = -0.4 W_{AB}, 0 = -1.6 - 0.3 W_{AB}i_{X}$ 0.4 m 0.4



$$U_0^2 = 2a_0 s$$
, $a_0 = \frac{(1.2)^2}{2(2.4)} = 0.30 \text{ m/s}^2$





$$a_{B}^{2} = \sqrt{(0.30 + 0.30)^{2} + (5.76)^{2}}$$

$$= 5.79 \text{ m/s}^{2}$$

5/133
$$y$$

$$\beta = \sin^{-1} \frac{0.5 - 0.5 \sin 30^{\circ}}{1.2}$$

$$= 12.02^{\circ}$$

$$\{v_{B} = 4.38 \text{ m/s (Prob. 5/68)}$$

$$\omega = 3.23 \text{ rad/s}$$

$$v_{A} = 3 \text{ m/s} = \text{constant}$$

$$\underline{\alpha}_{B} = \underline{\alpha}_{A} + \underline{\alpha}_{B/A} = \underline{\alpha}_{A} + \underline{\alpha}_{X} \underline{r}_{B/A} - \underline{\omega}^{2} \underline{r}_{B/A}$$

$$\underline{\alpha}_{B+} \left(\sin 30^{\circ} \underline{i} - \cos 30^{\circ} \underline{j} \right) + \frac{4.38^{2}}{0.5} \left(\cos 30^{\circ} \underline{i} + \sin 30^{\circ} \underline{j} \right)$$

$$= \underline{0} + \underline{\alpha}_{X} \underline{k}_{X} \underline{l}. 2 \left(-\cos 12.02^{\circ} \underline{i} + \sin 12.02^{\circ} \underline{j} \right)$$

$$- 3.23^{2} \left(1.2 \right) \left(-\cos 12.02^{\circ} \underline{i} + \sin 12.02^{\circ} \underline{j} \right)$$

Corry out vector algebra & equate coefficients:

$$i: \frac{1}{2}a_{8t} + 33.3 = -0.250x + 12.28$$

$$i : -\frac{13}{2}a_{8t} + 19.21 = -1.174 \times -2.61$$

Solution:
$$a_{8t} = -23.9 \text{ m/s}^2$$
 $d = -36.2 \text{ rod/s}^2$

$$\frac{5/134}{\omega_{AB}} = \frac{v_{A/\ell}}{v_{B}} = 0$$

$$\frac{v_{B}}{v_{B}} = 0 \quad 50 \quad (\alpha_{B})_{n} = 0$$

$$\frac{l}{v_{A}} = 0$$

$$\frac{l}{v_{B}} = \alpha_{A} + (\alpha_{B/A})_{n} + (\alpha_{B/A})_{\ell}$$

$$\alpha_{B} = \alpha_{A} + (\alpha_{B/A})_{n} + (\alpha_{B/A})_{\ell}$$

$$\alpha_{B} = 0 \quad + (\alpha_{B/A})_{n} + 0$$

$$\alpha_{B} = 0 \quad + (\alpha_{B/A})_{$$

$$\omega_{AB} = \frac{V_{A}/\ell}{V_{B}} = 0$$

$$V_{B} = 0 \quad 50 \quad (a_{B})_{n} = \frac{V_{B}^{2}}{r} = 0$$

$$a_{B} = a_{A} + (a_{B/A})_{n} + (a_{B/A})_{\ell}$$

$$a_{B} = 0 + (a_{B/A})_{n} + 0$$

$$(a_{B/A})_{\ell} = (a_{B/A})_{n} = 0$$

5/135

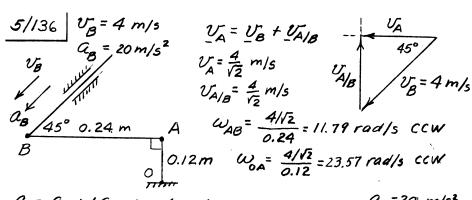
$$C \qquad V_B = 0 \quad so \quad (a_B)_n = 0$$

$$a_B = (a_B)_{\frac{1}{4}} = r\alpha$$

$$\omega \qquad A \qquad B \qquad \omega_{BA} = \frac{V_A}{l} = \omega$$

$$a_B = a_A + (a_{B/A})_n + (a_{B/A})_{\frac{1}{4}} \qquad (a_{B/A})_n = l\omega^2 \quad a_A = l\omega^2$$

$$a_A = l\omega^2 \qquad (a_{B/A})_n = BA \omega_{BA}^2 = l\omega^2 \qquad (a_{B/A})_{\frac{1}{4}} = 0$$
Thus $r\alpha = 2l\omega^2$, $\alpha = 2l\omega^2/r$ cw

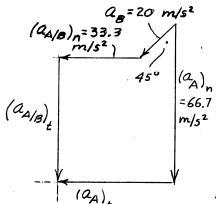


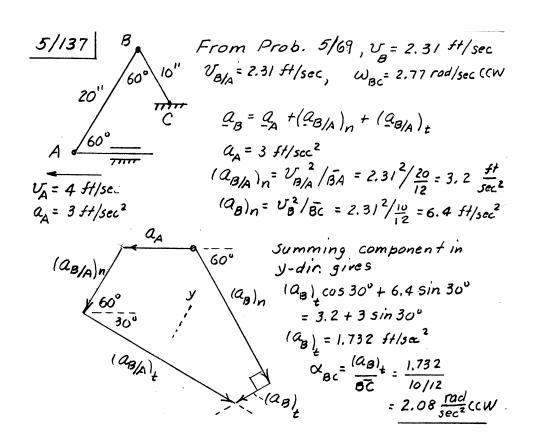
$$\underline{Q}_{A} = \underline{Q}_{B} + (\underline{Q}_{A/B})_{n} + (\underline{Q}_{A/B})_{t}
(\underline{Q}_{A/B})_{n} = 0.24(11.79)^{2} = 33.3 \text{ m/s}^{2}
(\underline{Q}_{A})_{n} = 0.12(23.57)^{2} = 66.7 \text{ m/s}^{2}$$

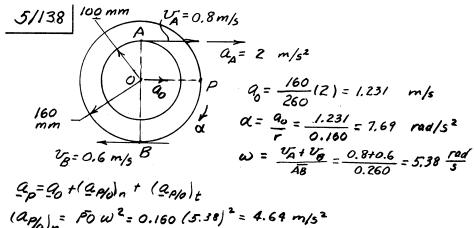
From diagram
$$(a_{A})_{\xi} = 33.3 + 20/12 = 47.5 \text{ m/s}^{2}$$

$$\alpha_{A} = \frac{(a_{A})_{\xi}}{\overline{OA}} = \frac{47.5}{0.12} = 396 \text{ rad/s}^{2}$$

$$CCW$$







$$Q_{p} = Q_{0} + (Q_{p})_{n} + (Q_{p})_{t}$$

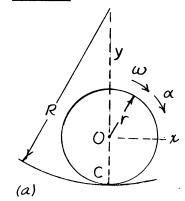
$$(Q_{p})_{n} = P_{0} \omega^{2} = 0.160 (5.38)^{2} = 4.64 \text{ m/s}^{2}$$

$$(Q_{p})_{t} = P_{0} \omega = 0.16 (7.69) = 1.231 \text{ m/s}^{2} \qquad (Q_{p})_{n} \quad P_{0} = Q_{0}$$

$$Q_{p} = \sqrt{(4.64 - 1.231)^{2} + (1.231)^{2}} = 3.62 \text{ m/s}^{2}$$

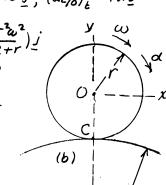
$$(Q_{p})_{t} = Q_{0} = Q_{0} = Q_{0}$$

From Prob. 5/81, WAB = 0.214 K, WCZ 0.429 K Tod $\omega = 0.5 \, \text{rad/s} \, \text{y} \qquad \stackrel{Q}{=} \alpha_B + (Q_{A|B})_n + (Q_{A|B})_t - - - - (\alpha)$ $Q_A = \omega_{CA} \times (\omega_{CA} \times C_A) + Q_{CA} \times C_A$ = $(0.429)^2 (k \times [k \times \{0.12 i + 0.16 j\}])$ 160 + de k x (0.12 + 0.16 j) mm = 0.1837(-0.12i - 0.16j)mm 0 +0.120 caj -0.160 caj ag= wx(wx 108)=(0.5)2(0.12)(-i) = -0.03j m/52 (QA/B) = WABX (WABX [BA) = (0.214)2 (Kx[KX {0.24i+0.04j}]) = 0.0459 (-0.24i -0.04j) m/32 (QAIB) = QABK × [BA = QABK × (0.24i + 0.04i) = QAB(0.24j - 0.04i) Substitute terms into Eq. (a) 4 equate separately i si coefficients & get $\alpha_{AB} - 4\alpha_{CA} = 0.2755$ 20/AB - 0.02041 Solve \$ get de - 0.0758 rad/s2 , da= -0.0277 rad/s2 CCA = -0.0758 k rad/s2



(b)
$$(Q_0)_n = \frac{v_0^2}{R+r}(-\underline{i}); (Q_0)_{\underline{i}} = r\alpha \underline{i}$$

 $(Q_0)_n = r\omega^2\underline{j}; (Q_0)_{\underline{i}} = -r\alpha \underline{i}$
Add $Q_0 = r\omega^2\underline{j}; (Q_0)_{\underline{i}} = -r\alpha \underline{i}$



$$(\underline{Q}_0)_n = \frac{v_0^2}{R-r} \underline{j} = \frac{r^2 \omega^2}{R-r} \underline{j}$$

$$(\underline{a}_{0})_{\underline{t}} = r\alpha \underline{t}'$$

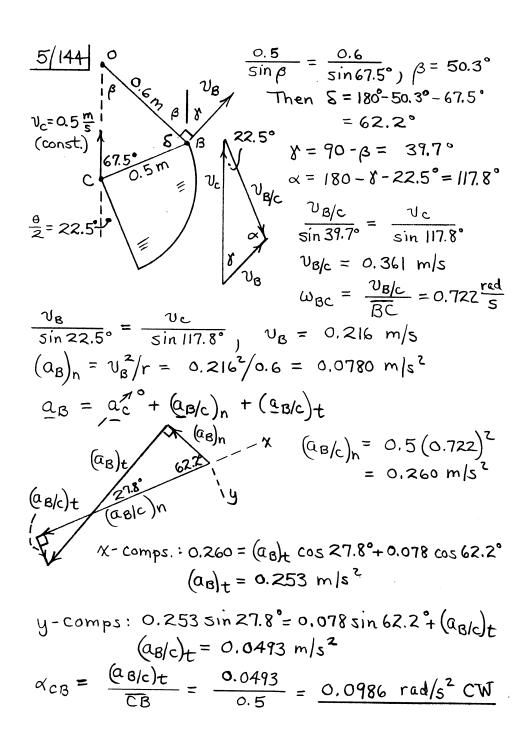
$$(\underline{a}_{6/0})_{\underline{n}} = r\omega^{2}\underline{t}'$$

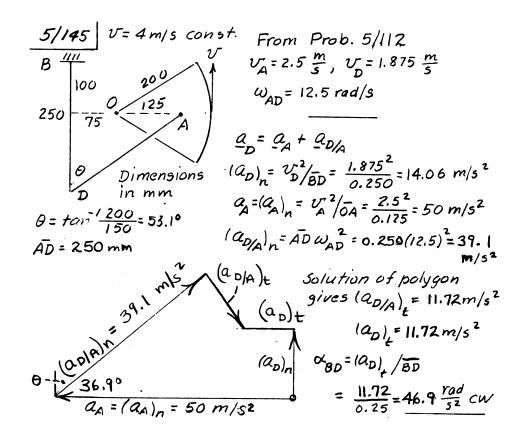
$$(Q_{c/0})_{\xi} = -r\alpha i$$

Add 8 set $a_{\xi} = \frac{r^2\omega^2}{R-r} i + r\omega^2 i = \frac{r\omega^2}{1-r/R} i$

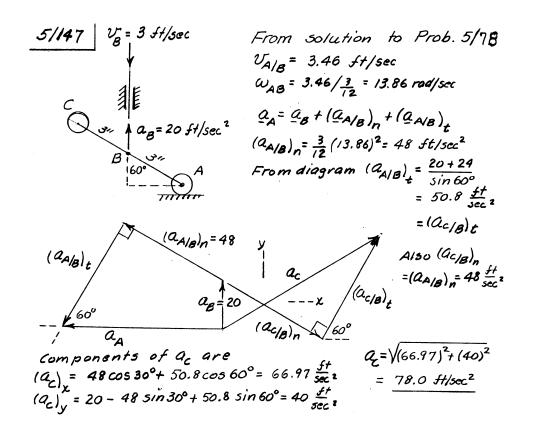
5/141 y ω_{AB} ω_{B} $\omega_{$

$$\frac{5/|43|}{(450)^{2} + (100)^{2}} = 439 \text{ mm} \qquad \frac{B}{100} \qquad \frac{O}{0} = \frac{VB}{CB} = \frac{OB}{CB} \qquad \frac{OB}{CB} \qquad \frac{O}{CB} = \frac{OB}{CB} \qquad \frac{O}{CB} \qquad \frac{O}{CB} = \frac{OB}{CB} \qquad \frac{O}{CB} \qquad \frac{O}{CB} = \frac{OB}{CB} \qquad \frac{OB}{CB} = \frac{OB}{$$

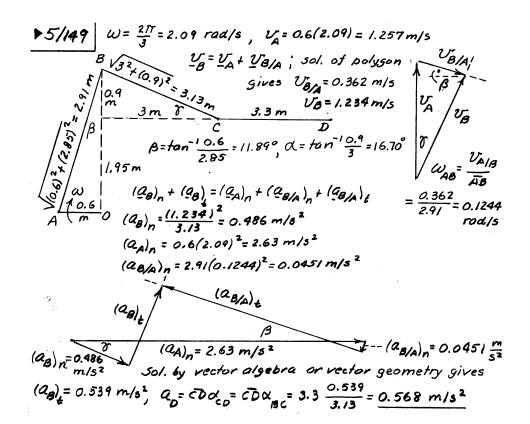


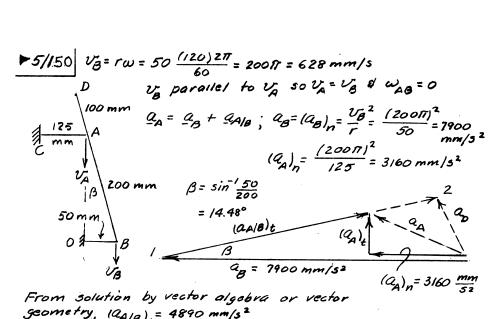


 $\frac{5/|46}{|A|} = \frac{1}{0.2} \frac{2}{\sqrt{3}} \frac{1}{k} = \frac{20}{\sqrt{3}} \frac{1}{k} rod/s$ $\frac{\omega_{AB}}{|A|} = \frac{2}{0.2} \frac{2}{\sqrt{3}} \frac{1}{k} = \frac{20}{\sqrt{3}} \frac{1}{k} rod/s$ $\frac{\omega_{AB}}{|A|} = \frac{2}{0.2} \frac{2}{\sqrt{3}} \frac{1}{k} = \frac{20}{\sqrt{3}} \frac{1}{k} rod/s$ $\frac{\omega_{AB}}{|A|} = \frac{2}{\sqrt{3}} \frac{1}{k} + \frac{20}{\sqrt{3}} \frac{1}{k} \frac{1}{k} \frac{1}{k} \frac{1}{k}$ Thus $a_{B} \stackrel{!}{=} 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = \frac{40}{\sqrt{3}} \frac{1}{\sqrt{3}} + \frac{\omega_{AB}}{|A|} \frac{1}{\sqrt{3}} \frac{1}{\sqrt{3}} \frac{1}{\sqrt{3}} \frac{1}{\sqrt{3}} \frac{1}{\sqrt{3}}$ Thus $a_{B} \stackrel{!}{=} 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{2} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{2} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{2} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{\sqrt{3}} (\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_{AB}}{|A|} = 0 + \frac{40}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k}) + \frac{20}{3} (-\sqrt{3} \frac{1}{k} + \frac{1}{k})$ $\frac{\omega_$



-0.1 ω_{on} j - 0.2 ω_{on} i = 0.05πi - 0.3 ω_{AB} j - 0.05 ω_{AB} i Equate like Coefficients: $\begin{cases} ω_{AB} = -0.286 \text{ k rad/s} \\ ω_{OA} = -0.857 \text{ k rad/s} \end{cases}$ Noω, $α_A = α_B + (α_A/B)_N + (α_A/B)_+ *$ $α_A = -ω_{OA}^2 r_{OA} + α_{OA} α_{A} α_{$



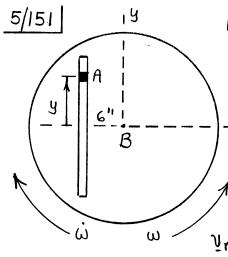


From solution by vector algebra or vector geometry, 124/8) = 4890 mm/s2

$$Q_{D} = Q_{B} + Q_{D|B}; \quad Q_{D|B} = (Q_{D|B})_{t} = \frac{\overline{BD}}{\overline{BA}} (Q_{A|B})_{t} = \frac{300}{200} (4890) = 7340 \frac{mm}{52}$$

$$Q_{D} = \sqrt{(7340 \sin |4.48^{\circ})^{2} + (7900 - 7340 \cos |4.48^{\circ})^{2}}$$

$$= 1997 \text{ mm/s}^{2}$$



Attach Bxy to disk as shown. In Eqs. 5/12 & 5/14:

$$\overline{\Omega} = 2K \frac{26c}{\sqrt{\sigma}} = 3K \frac{26c}{\sqrt{\sigma}}$$

$$\underline{r} = -0.5i + 0.667j$$
 ft

Eq.
$$5/12$$
, $v_A = v_B + w_X r + v_{rel}$, yields
$$v_A = -3.33 \dot{l} - 4.5 \dot{j} + \sqrt{sec}$$

$$\frac{5/152}{2} \qquad \underline{v} = v(-\sin\theta j + \cos\theta k)$$

$$a_{cor} = 2u \times v$$

$$= 2\Omega k \times v(-\sin\theta j + \cos\theta k)$$

$$= 2\Omega v \sin\theta i \quad (west)$$

$$= 2\Omega v \sin\theta i \quad (west)$$

For $v = 500 \, \text{km/h}$

(a) Equator,
$$\theta = 0$$
: $\alpha_{cor} = 0$

(b) North pole,
$$\Theta = 90^{\circ}$$
: $a_{cor} = 2(7.292 \cdot 10^{-5}) \frac{500}{3.6}$
= 0.0203 m/s²

The track provides the necessary westward acceleration so that the velocity vector is properly rotated and reduced in magnitude. Constraints are $v_0 = -rw \neq a_0 = -ra$. So $w = -\frac{v_0}{r} = -\frac{3}{0.30} = 10 \text{ rad/s}$ $w = -\frac{v_0}{r} = -\frac{3}{0.30} = 10 \text{ rad/s}$ $w = -\frac{q_0}{r} = -\frac{3}{0.30} = -16.67 \text{ rad/s}^2$ Use the frame Oxy as disk-fixed.

(5/12): $v_A = v_0 + \omega \times r + v_{rel}$ (5/14): $a_A = a_0 + \alpha \times r + \omega \times (\omega \times r) + 2\omega \times v_{rel} + a_{rel}$ Ingredients: $v_0 = -3i \text{ m/s}$ $v_0 = -3i \text{ m/s}$ $v_0 = -3i \text{ m/s}$ $v_0 = -3i \text{ m/s}$ Substitute into (5/12) $v_0 = -3i \text{ m/s}$ $v_0 = -3.4i \text{ m/s}$

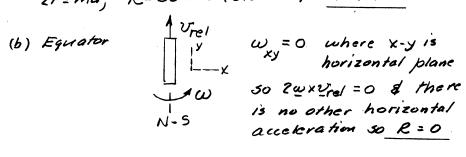
5/154 Let the Bxy axes shown in the figure be attached to the disk of the merry-go-round.

 $\hat{\Delta}^{\text{Lel}} = -\nabla r q \hat{1}$ $\hat{\sigma} = \hat{\sigma} + \nabla r \hat{r} \times q \hat{r} + \hat{\Lambda}^{\text{Lel}}$ $\hat{\sigma} = \hat{\sigma} + \nabla r \hat{r} \times q \hat{r} + \hat{\Lambda}^{\text{Lel}}$

This result does not depend on the location of P.

5/155 | Vrel (a) North pole 2wx Vrel | R

only horizontal component of acceleration 15 | 2wx vel = 2(0.7292)(10-4)(15) = 0.00219 m/52 EF= ma; R= 50000 (0.00219) = 109.4 N



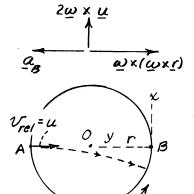
5/157 From Prob. 5/156 $V_{rel} = 20i - 9j \, m/s$ $W = 0.15k \, rad/s$ $Q_A = Q_B + W \times (W \times r) + W \times r + 2W \times V_{rel} + Q_{rel}$ $Q_A = 0$, $Q_B = \frac{V_B^2}{R}(-i) = -\frac{15^2}{100}i = -2.25i \, m/s^2$ $W \times (W \times r) = 0.15k \times (0.15k \times [-40i] = 0.90i \, m/s^2$ $W \times r = 0$ $ZW \times V_{rel} = 2(0.15k) \times (20i - 9j) = 2.7i + 6j \, m/s^2$ Thus $0 = -2.25i + 0.90i + 0 + 2.7i + 6j + Q_{rel}$ $Q_{rel} = -1.35i - 6j \, m/s^2$

5/158 x-y axes attached to B and have the angular velocity $W = \frac{10}{180}\pi = 0.1745 \text{ rad/min}$ $V_A = 12 \text{ knots}$ A 2 n. mi $A = -\frac{1}{2} + \frac{1}{2} + \frac{1}{2} = \frac{1}{2} + \frac{1}{2} = \frac{1}{2}$

$$\frac{5/159}{V_{A}} = \frac{540(1000)(-i) = -150i \text{ m/s}}{3600} = \frac{360(1000)(-i) = -150i \text{ m/s}}{3600} = \frac{360(1000)(-i) = -100i \text{ m/s}}{3600} = \frac{360(1000)(-i) = -100i \text{ m/s}}{3600} = \frac{3600(1000)(-i) = -100i \text{ m/s}}{3600} = \frac{36000(1000)(-i) = -100i \text{ m/s}}{36000} = \frac{360000(1000)(-i) = -10000(1000)(-i) = -10000(1000)(-i) = -10000(1000)(-i) = -10000(1000)(-i) = -10000(1000)(-i$$

5/160 Let P be a point on the road coincident with A. $Q_A = Q_p + 2\omega \times V_{re} + Q_{re}$ $E = A 2\omega \times V_{re} | For zero vertical acceleration,$ $TTTT P V_{re} | |2\omega \times V_{re}| = R\omega^2$ $V_{re} = \frac{1}{2}R\omega$ For R = 6378 km, $\omega = 0.7292(10^{-4})$ rad/s, $V_{re} = \frac{1}{2}(6378\times10^3)(0.7292\times10^{-4}) = 233$ m/s
or $V_{re} = 233(3.6) = 837$ km/h

5/16/ (accel. of ball) = $a = a_B + w \times (w \times r) + 2w \times v_{rel}$ Once ball leaves A, its horiz. $+ a_{rel}$ accel. is zero, a = 0



$$\alpha_{\beta} = r\omega_{j}^{2}$$

$$\omega \times (\omega \times \Gamma') = 2r\omega^{2}(-j)$$

$$\omega \times (\omega \times \Gamma)$$

$$\omega \times (\omega \times \Gamma)$$

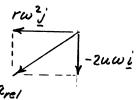
$$\omega \times (\omega \times \Gamma)$$

$$2\omega \times V_{rel} = 2\omega \times \omega \times (\omega - j) = 2\omega \omega_{i}$$

$$\alpha_{rel} = -r\omega_{j}^{2} + 2r\omega_{j}^{2} - 2\omega \omega_{i}$$

$$= r\omega_{j}^{2} - 2\omega \omega_{i}$$

$$\alpha_{rel} = \omega \sqrt{r^{2}\omega^{2} + 4\omega^{2}}$$



5/162

A $T = (20+b)\dot{i} = 25\dot{i}$ ft $V_{re} | = \dot{r}\dot{i} = 2\dot{i}$ ft/sec $Q_{re} | = \dot{r}\dot{i} = -1\dot{i}$ ft/sec $Q_{re} | = \dot{r}\dot{i} = 2\dot{i}$ ft/sec

(a) $Q_A - Q_B = -10.42 i + 5.70 j - (-10)(0.866 i - 0.5 j)$ = -1.76 i + 0.70 j St/sec with respect to truck

5//63

By Attach x-y axes to B

$$V_A = V_B + \omega \times r + v_{rel}$$
 $V_A = V_S + \omega \times r + v_{rel}$
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So Ure 1 = 0

5/164 From Prob. 5/163 $v_{rel} = 0$, $w = -\frac{v}{R}k$ $w \times r = -v \sin \theta \dot{i} - v(1 - \cos \theta) \dot{j}$ $w \times (w \times r) = -\frac{v}{R}k \times [-v \sin \theta \dot{i} - v(1 - \cos \theta) \dot{j}]$ $= \frac{v^2}{R} \sin \theta \dot{j} - \frac{v^2}{R} (1 - \cos \theta) \dot{i}$ $\dot{w} \times r = 0$ $2w \times v_{rel} = 0$ $a_B = \frac{v^2}{R} \dot{i}$ $4a_A = a_B + \omega \times (w \times r) + \dot{w} \times r$ $4a_A = a_B + \omega \times (w \times$

$$\frac{5/165}{v_B = 480 \frac{44}{30} = 704 \text{ ft/sec}}$$

$$v_A = 360 \frac{44}{30} = 528 \text{ ft/sec}$$

$$v_A = v_B + \omega \times r + v_{rel}$$

Angular vel. of axes = $\underline{\omega} = \frac{UB}{P}(-\underline{k})$ = $\frac{-704}{9\times5280}\underline{k} = -0.01481\underline{k}$ rad/sec

$$v_{rel} = vel. \ of \ A \ rel. \ to \ B$$

$$r = 5(5280) \underline{i} = 26,400 \underline{i} \ ft$$

Thus 528(-0.707i-0.707j) = 704j-0.01481 k × 26,400 i + 0 rel

5/166 Refer to solution for Prob. 5/165.

 $\underline{a}_{A} = \underline{a}_{B} + \underline{\omega} \times \underline{r} + \underline{\omega} \times (\underline{\omega} \times \underline{r}) + 2\underline{\omega} \times \underline{\sigma}_{rel} + \underline{a}_{rel}$

 $a_{A} = 0$, $a_{B} = \frac{U_{B}^{2}}{\rho} i = \frac{704^{2}}{9 \times 5280} i = 10.43 i \text{ ft/sec}^{2}$ $\dot{\omega} \times r = 0$

 $\omega \times (\omega \times r) = -0.01481 \, \underline{k} \times (-0.01481 \, \underline{k} \times 26,400 \, \underline{i}) = -5.79 \, \underline{i} \, ft/sec^2$ $2 \omega \times \underline{\nu}_{rel} = 2 \, (-0.1481 \, \underline{k}) \times (-373 \, \underline{i} - 686 \, \underline{j}) = 11.05 \, \underline{j} - 23.0 \, \underline{i} \, ft/sec^2$

 $a_{rel} = 0 - 10.43i - 0 + 5.79i - 11.05j + 20.3i = 15.69i - 11.05j ft/sec^2$ where $a_{rel} = 19.19 \text{ ft/sec}^2$

$$\frac{5/167}{2}$$

$$\frac{1}{2}$$

mechanism available, the ball will drift to the east (relative to the ground) with an acceleration of magnitude acor.

$$y' = 2\Omega V \sin \theta$$

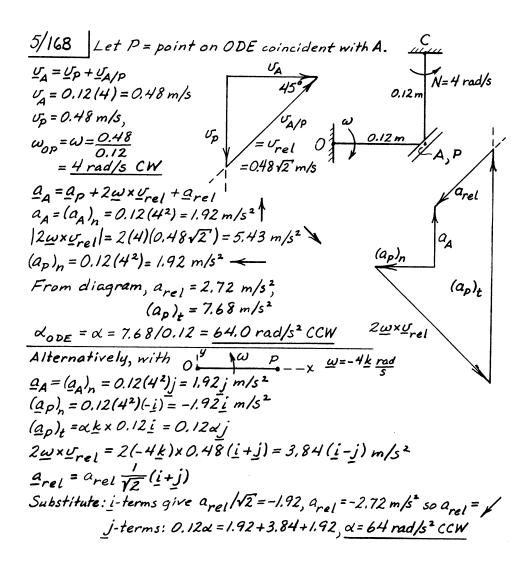
$$S = \frac{1}{2} \alpha_{x'} + \frac{1}{2} = \frac{1}{2} (2\Omega V \sin \theta) (\frac{1}{2})^{2}$$

$$= \frac{\Omega L^{2}}{V} \sin \theta \quad (assumes S << L)$$

$$X' = \frac{1}{2} \frac{1}{2} \sin \theta \quad (assumes S << L)$$

$$X' = \frac{1}{2} \frac{1}{2} \sin \theta \quad (assumes S << L)$$

With $\Omega = 7.292 (10^{-5})$ rad/sec, 1 = 15 ft/sec, L = 60 ft, $40 = 40^{\circ}$: 8 = 0.01125 ft (0.1350 in.)



5/169 A
$$V_A = V_B + \omega \times \Gamma + V_{rel}$$
 $V_A = V_B + \omega \times \Gamma + V_{rel}$
 $V_B = 20i \ m/s$
 $V_B = 20i \ m/s$
 $V_B = 20i \ m/s$
 $V_A = V_B = 20i \$

$$\frac{5/170}{\Gamma} = 2(180 - \frac{180}{12}) + 20 = 125.4 \text{ ft}$$

$$\Gamma_{\chi} = \Gamma_{y} = 125.4 \frac{12}{2} = 88.7 \text{ ft}$$

$$\Gamma = 88.7 (i + i) \text{ ft}$$

$$\frac{180}{14} = -44i \text{ ft/sec}$$

$$\frac{180}{12} = 44j \text{ ft/sec}$$

$$\frac{45^{\circ}}{180} = 44j \text{ ft/sec}$$

Substitute & obtain vrel = -22.3i-65.7j ftsec

$$\underline{\dot{\omega}} = \underline{0}$$

$$\underline{\dot{\alpha}} = \underline{\alpha}_{B} + \underline{\alpha}_{X}\underline{r} + \underline{\omega}_{X}(\underline{\omega}_{X}\underline{r}) + \underline{\alpha}_{X}\underline{\nu}_{R} + \underline{\alpha}_{R}\underline{\nu}_{R}$$

$$\underline{\dot{\alpha}} = \underline{0}$$

$$\underline{\dot{\alpha}} = \underline{0}$$

Substitute & obtain are = -16.06 + 27.0 ft/sec2

5/171 Y $A_{b}(\theta=90^{\circ})$; $A_{a}(\theta=0)$ For circular orbit $V=R\sqrt{g/r}$ A_{b} A_{b} A

(b) 0=90°, [= (42171-30000)] = 12171] km Vre1=-110701 - (-131251) - 0.4375 k × 12171] = 73801 km/h 5/172 $\Gamma = 8i ft$, $V_{rel} = ri = 2i ft/sec$, $Q_{rel} = ri = -1i ft/sec^2$ $W = \omega k = \frac{2\pi}{10} k = 0.628 k rad/sec$, $\dot{\omega} = 0$ $V = \omega k = \frac{2\pi}{10} k = 0.628 k rad/sec$, $\dot{\omega} = 0$ V = 0 = 0, $Q_{B} = Q_{0} = 0$ V = 0 = 0, $V_{A} = 0$, $V_{C} = 0$, $V_{C} = 0$ $V_{A} = 0$, $V_{C} = 0$, $V_{C} = 0$ $V_{C} = 0$, $V_{C} = 0$, $V_{C} = 0$ $V_{C} = 0$, $V_{C} = 0$, $V_{C} = 0$ $V_{C} = 0$, $V_{C} = 0$, $V_{C} = 0$ $V_{C} = 0$, $V_{C} = 0$ $V_{C} = 0$, $V_{C} = 0$ $V_$

5/173 Let Oxy be attached to OA. Eq. (5/12): ω_{BC} k x 0.2 (cos60° i + sin 60° j) = - 3k x 0.2i + Vrel i 0.10 WBC j - 0.2 3 WBC = - 0.6 j + Vrel 2 i: -0.1732 Wec = Vrel } Wec = -16 rad/s j: 0. 10 MBC = -0.6) Vrel = + 1.039 m/s Now Eq. (5/14): OB = OO + QXI + MX(MXI) + SMXjul + and aB = WBC X (WBC X [B/C) + QBC X [B/C = 62.02(-cas 60°i-sin60°j) + aBCKX 0.2 (+cos 60°i+sin60°j) = -3.62-6.24j + 0.100 BC j-0.2 3 aBC L $\vec{a}_0 = \vec{o}$, $\vec{L} = \vec{L}_{B/0} = \vec{o} \cdot \vec{S}_1$, $\vec{n} = \vec{n}_0 \vec{v} = -3\vec{K} \cdot \frac{2}{2} \vec{x} = \vec{a}_0 \vec{v} = \vec{o}$ are = are i > Substitute into (5/14) & solve to obtain $\frac{\alpha_{BC} = 0}{\text{Absolute motion approach}}$, $\alpha_{R} = -1.8 \text{ m/s}^2$ $2\beta + \theta = 0 \Rightarrow \frac{\ddot{\theta} = \alpha_{SC} = 0 !!}{\theta}$

5/174 x-y axes are attached to $V_{A} = 200(10) = 2000 \text{ mm/s}$ attached to $V_{B} = 000 \text{ mm/s}$ $V_{A} = 000 \text{ mm/s}$ $V_{B} = 000 \text{ mm/s}$ $V_{A} = 000 \text{ mm/s}$ $V_{A} = 000 \text{ mm/s}$ $V_{B} = 000 \text{ mm/s}$ $V_{B} = 000 \text{ mm/s}$ $V_{A} = 000 \text{ mm/s}$ $V_{B} = 000$

5/175 From Prob. 5/58 $\omega_2 = \omega = 1.923 \ rad/s \ (=-\beta)$ $\omega_1 = 2 \ rad/s$ $\Gamma = \frac{0.2}{\sqrt{2}} \frac{\sin 20^{\circ}}{\sin 35.8^{\circ}} = 0.0827 \ m$ $0.2 \frac{\sin \beta}{\theta = 20^{\circ}} \frac{\sin \beta}{\sin 35.8^{\circ}} = 0.0827 \ m$ $0.2 \frac{\sin \beta}{\theta = 20^{\circ}} \frac{\sin \beta}{\sin 35.8^{\circ}} = 0.2 \frac{\sin \beta$

 $\omega = \omega k = \partial k, \alpha = \omega k$ $\chi \Gamma = Li, \gamma_{rel} = Li$ $\alpha_{rel} = Li$

 $\underline{V}_{c} = \underline{V}_{c}(\underline{i}\cos\theta - \underline{j}\sin\theta)$ $\underline{Q}_{c} = \underline{Q}_{c}(\underline{i}\cos\theta - \underline{j}\sin\theta)$

 $U = V_c + \omega \times r_c = V_c + \omega k \times h_j = (V_c \cos \theta - \omega h) \underline{i} - (V_c \sin \theta) \underline{j}$ $Q_{\beta} = Q_c + \omega \times r_{c\beta} + \omega \times (\omega \times r_{c\beta}) = Q_c + \alpha k \times h_j + \omega k \times (\omega k \times h_j)$ $= (Q_c \cos \theta - \alpha h) \underline{i} - (Q_c \sin \theta + h \omega^2) \underline{j}$

 $V_A = V_B + \omega \times \Gamma + V_{rel} = V_B + \omega \underline{k} \times \underline{L}\underline{i} + \underline{L}\underline{i}$ $V_A = (V_C \cos \theta - \omega h + \underline{L})\underline{i} + (\omega \underline{L} - V_C \sin \theta)\underline{j}$

 $\underline{\alpha}_{A} = \underline{\alpha}_{B} + \underline{\omega} \times \underline{r} + \underline{\omega} \times (\underline{\omega} \times \underline{r}) + 2\underline{\omega} \times \underline{U}_{rel} + \underline{q}_{rel}$ $= \underline{\alpha}_{B} + \underline{\omega} \underline{k} \times \underline{L}\underline{L} + \underline{\omega} \underline{k} \times (\underline{\omega} \underline{k} \times \underline{L}\underline{L}) + 2\underline{\omega} \underline{k} \times \underline{L}\underline{L} + \underline{L}\underline{L}\underline{L}$ $\underline{\alpha}_{A} = (\underline{\alpha}_{C} \cos \theta - \alpha h - \underline{L}\underline{\omega}^{2} + \underline{L}\underline{U})\underline{L} + (-\underline{\alpha}_{S} \sin \theta - h\underline{\omega}^{2} + \underline{L}\underline{\alpha} + 2\underline{\omega}\underline{L})\underline{L}$

►5/177 For circular orbit; At equator $g = 9.8/4 \, m/s^2$ $V_A = R\sqrt{9/(R+h)} = 6378\sqrt{\frac{9.814/1000}{6378 + 240}}(3600) = 27960 \, \frac{km}{h}$ $V_A = R\sqrt{9/(R+h)} = 6378\sqrt{\frac{9.814/1000}{6378 + 240}}(3600) = 27960 \, \frac{km}{h}$ $V_A = \frac{V_A^2}{R+h} = 9\left(\frac{R}{R+h}\right)^2 = 9.8/4\left(\frac{6378}{6378 + 240}\right)^2 = 9.115 \, m/s^2$ $V_B = Rw = 6378(0.7292)(10^{-4})(3600) = 1674 \, km/h$ $R = 6378 \, km$ $V_A = V_B + \omega \times \Gamma + V_{rel}$ $W = 0.7292(10^{-4})70d/s$ $W = 0.7292(10^{-4})(3600)(240)(-1)$ $W = 0.7292(10^{-4})70d/s$ $W = 0.7292(10^{-4})(3600)(240)(-1)$ $W = 0.7292(10^{-4})70d/s$ $W = 0.7292(10^{-4})(3600)(240)(-1)$ $W = 0.7292(10^{-4})(360$

5/178 y ap = accel. measured relative to constant velocity frame F. Therefore point 0 can be considered to be fixed so. 2= 36 km/h or 10 m/s 0.8 m 111111 0.8m $= \frac{1}{2} I_1 = 0.825 m$ $\beta = 10n^{-1} \frac{0.4}{1.6} = 14.04$ ° 25 (rel. to 0) = 10 m/s $\omega = (v_p/r_i)_K = [(5 \sin 14.04^\circ)/1.649]_K$ = 0.735 k rod/s (Une/) = 5 cos 14.04°(-i) = -4.85i m/s (Ure1) = Up tan | (4) = \frac{1}{2}(5) sin | ton | (4) = 0.1516 i m/s $Q_A = [5^2/0.4](-isin\beta-icos\beta) = -15.16L - 60.63j m/5^2$ $\omega \times \Gamma_1 = \omega K \times \Gamma_1 \dot{c} = 1.649 \omega \dot{j}, \quad \dot{\omega} \times \Gamma_2 = 0.825 \omega \dot{j}$ wx(wxr)=(0.735)2kx(kx1,649i)=-0.892i m/52 WX(wx5)=-0.446[m/s2 2wx(vre) = 2(0.735) xx (-4.85i) = -7.13j m/s2 2wx(vrel)2 = 2(0.735)Kx(0.15166)=0.2229j m/s2 (gre/) = r, 6, (gre/) = 1/2 ! 90=0 $a_{A} = a_{O} + \omega \times r_{i} + \omega \times (\omega \times r_{i}) + 2\omega \times (v_{rel}), + (a_{rel}),$ Substitute above terms, separate terms & get $\ddot{r} = -14.27 \, m/s^2$, $\dot{\omega} = -32.4 \, rad/s^2$ $a_B = a_0 + \omega \times r_2 + \omega \times (\omega \times r_2) + 2\omega \times (v_{rel})_2 + (q_{rel})_2$ where a= a (i sin B + i cos B) $\omega \times r_2 = -32.4 \, k \times 0.825 \, i = -26.75 \, j \, m/s^2$ Substitute & separate terms & get $\ddot{r}_{5} = -6.19 \text{ m/s}^{2}$ $a_B = -27.3 \, m/s^2$ (to the right)

$$\int_{-K-k\omega^{2}}^{\infty} d\omega = \frac{d\omega}{dt} = -K-k\omega^{2}$$

$$\int_{-K-k\omega^{2}}^{\infty} d\omega \int_{-K-k\omega^{2}}^{\infty} d\omega \int_$$

 $\frac{5/180}{\left(\frac{V^{2}}{\Gamma}\right)_{A}^{2}} = \frac{2}{3} \left(\frac{v^{2}}{3}\right)_{B}^{2}, \quad \frac{r=4.5 \text{ in.}}{\sqrt{2}}$

$$\chi_{c} = \frac{b}{2}\cos\theta + \frac{b\sqrt{3}}{2}\sin\theta$$

$$\dot{\chi}_{c} = -\frac{b}{2}\dot{\theta}\sin\theta + \frac{b\sqrt{3}}{2}\dot{\theta}\cos\theta$$

$$\dot{\chi}_{c} = 0 \text{ when } \frac{b}{2}\dot{\theta}\sin\theta = \frac{b\sqrt{3}}{2}\dot{\theta}\cos\theta$$

$$50 \quad \theta = \tan^{2}\sqrt{3} = 60^{\circ}$$

5/182
$$v_A = v_C + v_A/c$$

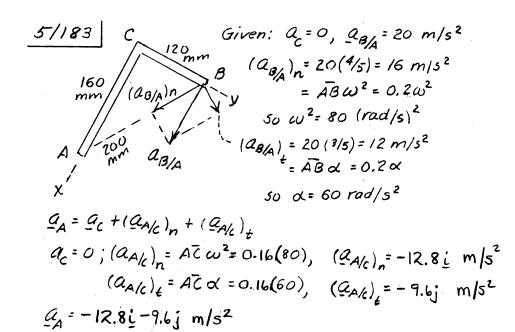
where $v_C = 120 \left(\frac{44}{30}\right) i = 176 i$ ft/sec

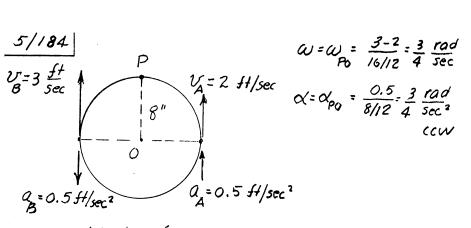
 $v_{A/C} = AC\Omega = 13 \left[800 \cdot \frac{2\pi i}{60}\right] = 1089$ ft/sec

So $v_A = 176 i + 1089 \left[+\cos 10^\circ i - \sin 10^\circ k\right]$
 $= 1249 i - 189.1 k$ ft/sec

 $v_{B/C} = v_{C} + v_{B/C}$
 $v_{B/C} = 1089 j$ ft/sec

So $v_B = 176 i + 1089 j$ ft/sec



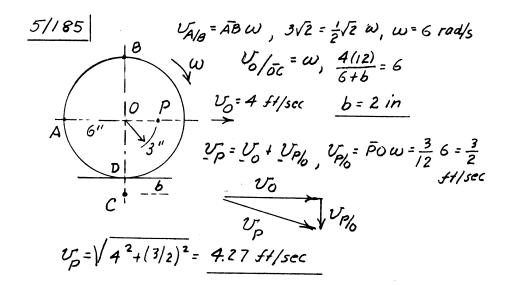


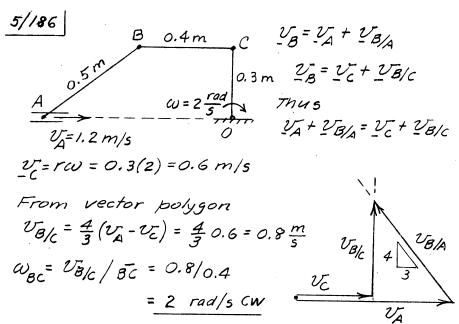
$$Q_{p} = Q_{0} + (Q_{p/0})_{n} + (Q_{p/0})_{t}$$

$$Q_{0} = Q_{0} + (Q_{p/0})_{n} = \frac{8}{12} (\frac{3}{4})^{2} = \frac{3}{8} ft/sec^{2}$$

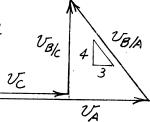
$$(Q_{p/0})_{t} = \frac{8}{12} \frac{3}{4} = \frac{1}{2} ft/sec^{2}$$

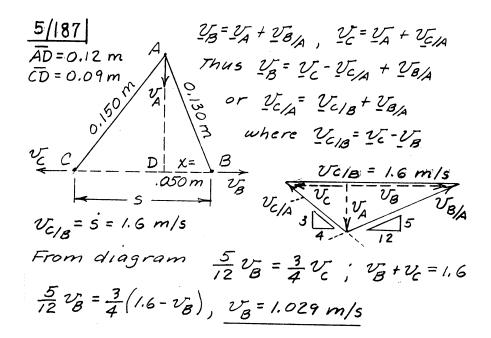
$$Q_{p} = \sqrt{(3/8)^{2} + (1/2)^{2}} = \frac{5/8}{8} ft/sec^{2}$$

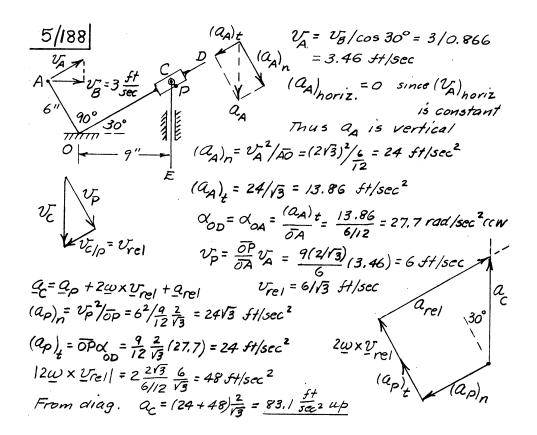


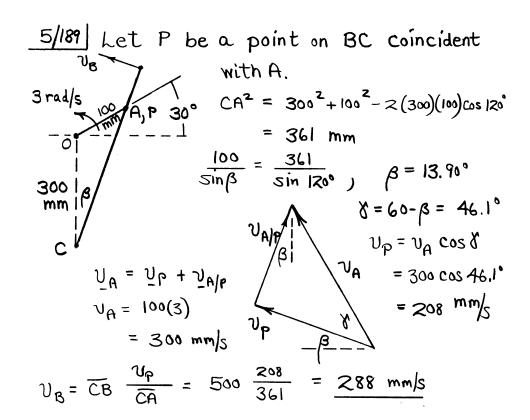


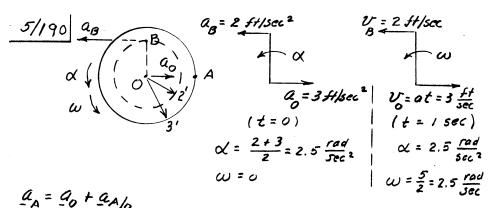
$$\omega_{BC} = \frac{V_{B/C}}{8C} = \frac{0.8}{0.4}$$
= 2 rad/s CW









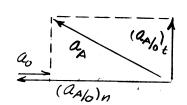


(a)
$$t=0$$
; $a_{A/o} = (a_{A/o})_{t} = 3(2.5) = 7.5 \text{ ft/sec}^{2}$

$$a_{A} = \sqrt{3^{2} + 7.5^{2}} = 8.08 \frac{\text{ft}}{\text{sec}^{2}} \qquad (a_{A/o})_{t}$$

(b)
$$t = 1 \sec_{1} (a_{A/o})_{n} = 3(2.5)^{2}$$

= 18.75 ft/sec^{2}
 $a_{A} = \sqrt{(18.75 - 3)^{2} + 7.5^{2}}$
= 17.44 ft/sec^{2}



5/191 V_A Law of cosines gives V_B Law of cosines gives $V_B = \frac{30}{30} \frac{h}{h} - \frac{1}{2} \frac{(R+h)^2}{2R^2} = \frac{R^2 + \Gamma^2 - 2Rr\cos{120^{\circ}}}{2R\cos{120^{\circ}}} \frac{(R+h)^2}{2R^2} = \frac{R^2 + \Gamma^2 - 2Rr\cos{120^{\circ}}}{2R^2} \frac{(6378)^2 + \Gamma^2}{2R^2} \frac{(6378)^2 + \Gamma^2}{2R^2} \frac{(6378)^2 + 4(2591200)}{2R^2} \frac{(6378)^2 + 4(25$

$$\frac{5/192}{a_{c} = a_{o} + (a_{c/o})_{n} + (a_{c/o})_{t}} = r\alpha$$

$$\underline{a_{c} = a_{o} + (a_{c/o})_{n} + (a_{c/o})_{t}}$$

$$\underline{a_{o} = r\alpha \underline{i} + \frac{(r\omega)^{2}}{R-r}\underline{j}}$$

$$(\underline{a_{c/o}})_{n} = r\omega^{2}\underline{j}, (\underline{a_{c/o}})_{t} = -r\alpha \underline{i}$$

$$\underline{a_{c} = r\alpha \underline{i} + \frac{(r\omega)^{2}}{R-r}\underline{j} + r\omega^{2}\underline{j} - r\alpha \underline{i}}, \underline{a_{c} = \frac{r\omega^{2}}{1-r/R}\underline{i}}$$

$$\underline{a_{A} = a_{o} + (\underline{a_{A/o}})_{n} + (\underline{a_{A/o}})_{t}}$$

$$(\underline{a_{A/o}})_{n} = -r\omega^{2}\underline{j}, (\underline{a_{A/o}})_{t} = r\alpha \underline{i}$$

$$\underline{a_{A} = r\alpha \underline{i} + \frac{(r\omega)^{2}}{R-r}\underline{j} - r\omega^{2}\underline{j} + r\alpha \underline{i}}, \underline{a_{A} = 2r\alpha \underline{i} + r\omega^{2}\frac{2r/R-1}{1-r/R}\underline{j}}$$

$$\underline{a_{A} = r\alpha \underline{i} + \frac{(r\omega)^{2}}{R-r}\underline{j} - r\omega^{2}\underline{j} + r\alpha \underline{i}}, \underline{a_{A} = 2r\alpha \underline{i} + r\omega^{2}\frac{2r/R-1}{1-r/R}\underline{j}}$$

For constant length,
$$V_B = V\cos\theta$$

$$V_B \qquad \omega = V_B/r$$

$$\omega = \frac{V\cos\theta}{r}$$

$$\omega_{AC} = \frac{V\sin\theta}{AB}$$

$$But \Gamma\cos\theta + AB\sin\theta = D$$

$$\cos AB = \frac{1}{\sin\theta} (D - r\cos\theta)$$
Thus $\omega_{AC} = \frac{V\sin^2\theta}{D - r\cos\theta}$

$$C = \frac{V_A}{AB} = \frac{V_A}{AC} = \frac{V_A}{b\cos\theta}$$

$$B = \frac{Q_B}{B} = \frac{Q_A}{A} + (\frac{Q_{B/A}}{A})_n + (\frac{Q_{B/A}}{A})_t$$

$$Q_A = Q_A + (\frac{Q_{B/A}}{A})_n + (\frac{Q_{B/A}}{A})_t$$

$$Q_A = Q_A + (\frac{Q_{B/A}}{A})_n + (\frac{Q_{B/A}}{A})_t$$

$$Q_A = Q_A + (\frac{Q_{B/A}}{AB})_n + (\frac{Q_{B/A}}{AB})_t$$

$$Q_A = \frac{V_A^2}{b\cos^2\theta}$$

$$Q_A = \frac{V_A^2}{b\cos^2\theta} + \tan\theta = \frac{V_A^2}{b\cos^2\theta}$$

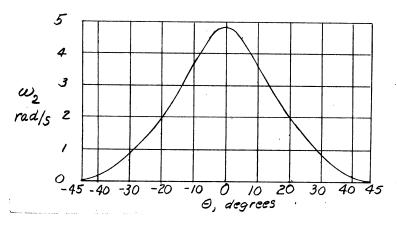
$$Q_A = \frac{(Q_{B/A})_t}{AB} = (\frac{V_A}{b})^2 \frac{\sin\theta}{\cos^3\theta}$$

= 2.05 m/s2

*\frac{\pm \frac{\pm \sigma \sigma \text{form Prob. 5/53} \text{ we have}}{\omega_2 = \text{\text{\text{os}} \left(\text{\text{os}} \left(\text{\text{\text{os}}}\beta)} \text{ where } \beta = \text{\text{os}} \beta \text{\text{os}} \beta \text{Also } \text{fan} \beta = \frac{\sin\theta}{\sin\theta} \text{\text{cos}} \text{\text{\text{os}}} \text{\text{os}}

For $\dot{\theta} = -2 \, rad/s$, $W_2 = 2 \, \frac{\cos(\theta + \beta)}{\sqrt{2} \cos \beta - \cos(\theta + \beta)}$

Set up program to compute B & wa & plot results.



$$\frac{*5/197}{\dot{\theta}} \stackrel{\stackrel{\cdot}{\theta}}{=} 100(1-\cos\theta) \ rod/s^{2}$$

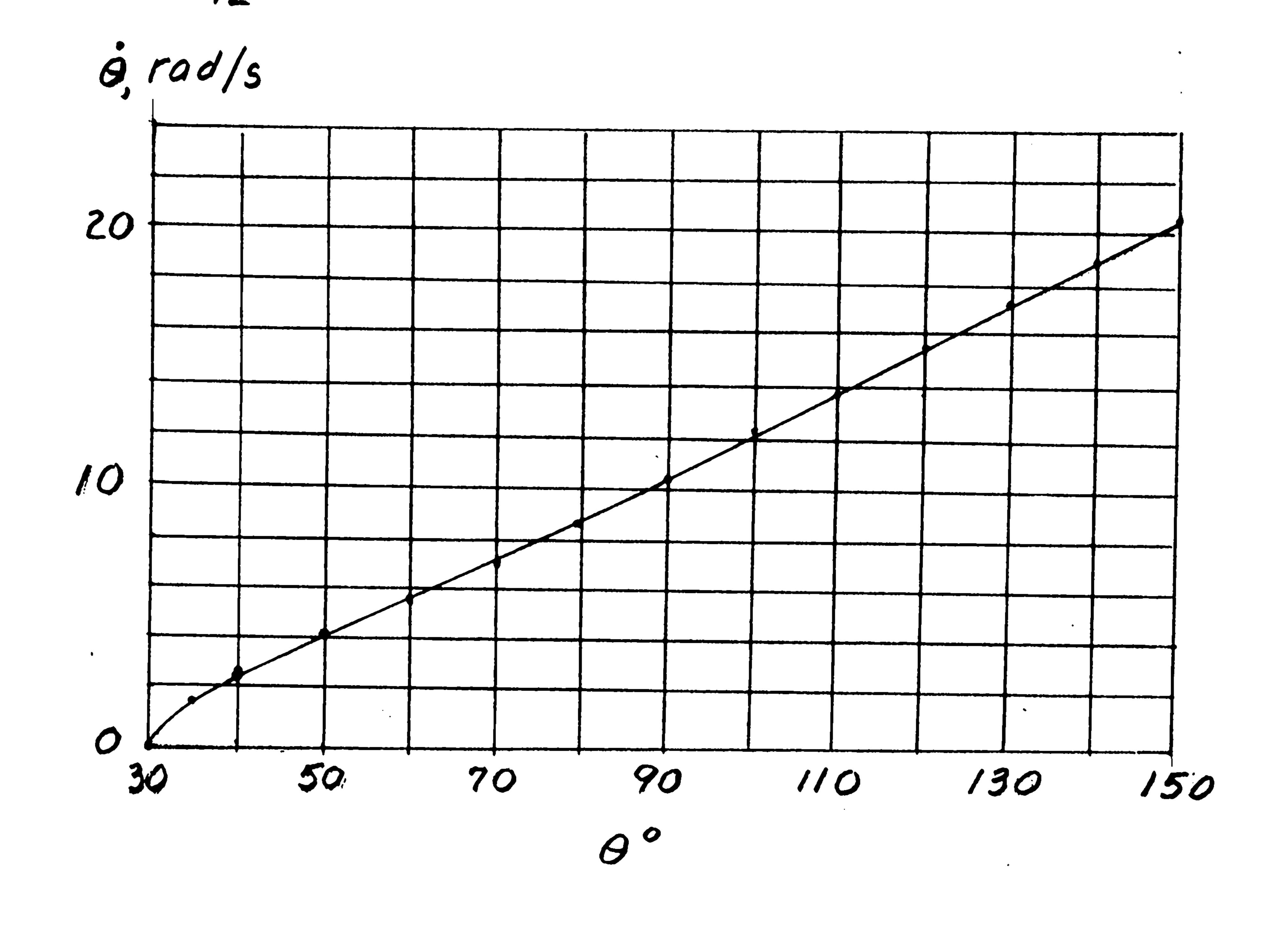
$$\frac{\dot{\theta}}{\dot{\theta}} \stackrel{\stackrel{\cdot}{\theta}}{=} 000 \int_{0}^{2} (1-\cos\theta) d\theta$$

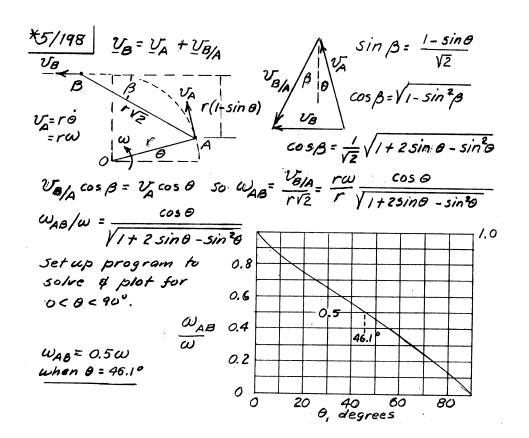
$$\frac{\dot{\theta}}{0} \stackrel{\stackrel{\cdot}{\theta}}{=} 200 \left(\theta - \sin\theta - 0.0236\right)$$

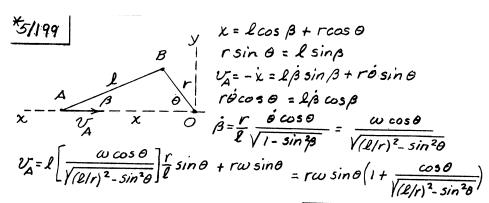
$$\frac{\dot{\theta}}{0} \stackrel{\stackrel{\cdot}{\theta}}{=} 200 \left(\theta - \sin\theta - 0.0236\right)$$

$$\frac{\dot{\theta}}{0} \stackrel{\stackrel{\cdot}{\theta}}{=} 10\sqrt{2} \sqrt{\theta - \sin\theta - 0.0236} \ rod/s$$

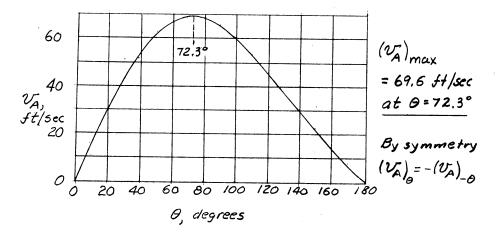
$$\int_{0}^{0} \frac{d\theta}{dt} = \int_{0}^{10\sqrt{2}} \frac{d\theta}{|\theta - \sin\theta - 0.0236} \ rod/s$$
Numerical integration gives $t = 0.0701 \text{ s}$







From Sample Problem 5/15 substitute l = |4/12| ft, r = 5/12| ft, $\omega = 1500(2\pi)/60 = 157.1 rad/sec & get$ $V_A = 65.45 sin \theta \left(1 + \frac{\cos \theta}{\sqrt{7.84 - \sin^2 \theta}}\right)$, Set up computer program $\sqrt{7.84 - \sin^2 \theta}$, $\sqrt{9}$ solve for $0 < \theta < 180^\circ$



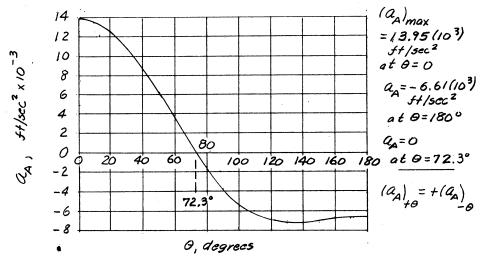
#5/200 From the results of 12rob. 5/199, we may write
$$a_{\Delta} = i \frac{d}{dt} \left\{ r w \sin \theta + r w \frac{\sin \theta \cos \theta}{\sqrt{(U/r)^2 - \sin^2 \theta}} \right\} \frac{(-\frac{1}{2} \sin 2\theta) \theta}{(U/r)^2 - \sin^2 \theta}$$

$$= r w \left\{ \theta \cos \theta + \frac{\sqrt{(U/r)^2 - \sin^2 \theta} (\theta \cos 2\theta) - \frac{1}{2} \sin 2\theta}{(U/r)^2 - \sin^2 \theta} \right\}$$
Which reduces to

which reduces to $Q = r\omega^{2} \left[\cos \theta + \frac{r}{\ell} \frac{1 - 2\sin^{2}\theta + \frac{r^{2}}{\ell^{2}} \sin^{4}\theta}{\left(1 - \frac{r^{2}}{\ell^{2}} \sin^{2}\theta\right)^{3/2}} \right]$

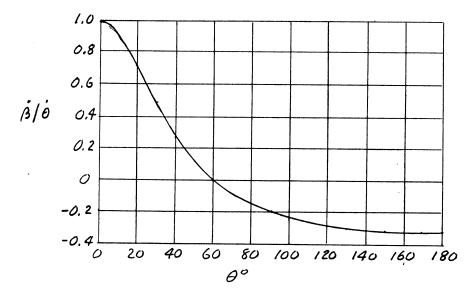
From Sample Problem 5/15 Substitule L=14/12 ft, r=5/12 ft, w=1500(211)/60=157.1 rad/sec & get $a_{A} = 1.028(10^{4}) \left[\cos \theta + 0.357 \frac{1 - 2\sin^{2}\theta + 0.1276\sin^{4}\theta}{(1 - 0.1276\sin^{2}\theta)^{3/2}} \right]$

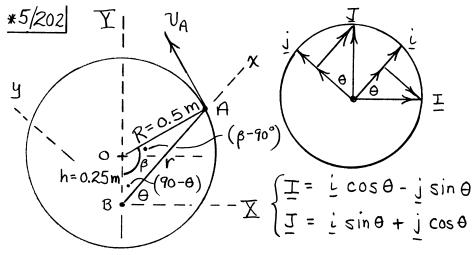
Set up computer program d solve for 0<0<180°



*
$$5/201$$

A $r \sin \theta = (2r - r\cos \theta) \tan \beta$
 $r \sin \theta = (2r - r\cos \theta) \tan \beta$
 $r \sin \theta = (2r - r\cos \theta) \tan \theta$
 $r \cos^2 \beta = \frac{(2 - \cos \theta)^2}{(2 - \cos \theta)^2 + \sin^2 \theta} = \frac{(2 - \cos \theta)^2}{5 - 4\cos \theta}$
 $r \sin \theta = \frac{(2 - \cos \theta)^2}{(2 - \cos \theta)^2 + \sin^2 \theta} = \frac{(2 - \cos \theta)^2}{5 - 4\cos \theta}$
 $r \sin \theta = \frac{(2r - r\cos \theta)}{(2 - \cos \theta)^2} = \frac{(2 - \cos \theta)^2}{(2 - \cos \theta)^2}$
 $r \sin \theta = \sin \theta$
 $r \sin \theta = (2r - r\cos \theta) + \cos \theta$
 $r \sin \theta = \sin \theta$
 $r \sin \theta = \cos \theta$
 $r \cos \theta =$





$$\frac{r^2 = h^2 + R^2 - 2hR \cos \beta}{R} = \frac{\cos \theta}{R} = \frac{\sin \beta}{r}, \ \theta = \cos^{-1} \left[\frac{R}{r} \sin \beta \right]$$

$$\underline{U}_{A} = R\dot{\beta} \left[-\sin(\beta - 90^{\circ}) \underline{I} + \cos(\beta - 90^{\circ}) \underline{I} \right]$$

$$\underline{\alpha}_{A} = R\dot{\beta}^{2} \left[-\cos(\beta - 90^{\circ}) \underline{I} - \sin(\beta - 90^{\circ}) \underline{J} \right]$$

Substitute the above transformation equations into the expressions for $y_A \notin q_A$ and simplify to obtain (with $c = \cos$, $s = \sin$)

$$\frac{\nabla_{A}}{\nabla_{A}} = R\dot{\beta} \left\{ \left[-c\theta s \left(\beta - 90^{\circ} \right) + s\theta c \left(\beta - 90^{\circ} \right) \right] \dot{c} \right. \\
+ \left[s\theta s \left(\beta - 90^{\circ} \right) + c\theta c \left(\beta - 90^{\circ} \right) \right] \dot{c} \right. \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - s\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right. \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s \left(\beta - 90^{\circ} \right) \right] \dot{c} \right] \\
+ \left[s\theta c \left(\beta - 90^{\circ} \right) - c\theta s$$

